# Improved learning graph based quantum algorithms for Triangle and Associativity 

Miklos Santha<br>CNRS, Université Paris Diderot<br>and<br>Centre for Quantum Technologies, NUS, Singapore<br>Joint work with<br>T. Lee CQT, Singapore and<br>F. Magniez CNRS, Paris

## Query complexity

Let $f: \mathcal{D} \rightarrow E$ with $\mathcal{D} \subseteq[d]^{n}$. Often $d=2$ and $E=\{0,1\}$.
Query complexity: Number of input queries needed to evaluate $f$.
Computational models: Deterministic, randomized, quantum
The gap between the deterministic and quantum complexities

- can be exponential [Simon'97, Shor'97]: Period finding, [EHK'99]: Hidden Subgroup Problem
- [BBCMW'01]: is at most polynomial for total functions


## Quantum query complexity

Theorem [HLS'07, R'11, LMRSSz'11]: Let $f: \mathcal{D} \rightarrow\{0,1\}$ with $\mathcal{D} \subseteq[d]^{n}$. Then

$$
\begin{aligned}
Q(f)=\underset{u_{x, i}}{\operatorname{minimize}} & \max _{x \in \mathcal{D}} \sum_{i \in[n]}\left\|u_{x, i}\right\|^{2} \\
\text { subject to } & \sum_{\substack{i \in[n] \\
x_{i} \neq y_{i}}}\left\langle u_{x, i} \mid u_{y, i}\right\rangle=1 \text { for all } f(x) \neq f(y),
\end{aligned}
$$

where $u_{x, i} \in \mathbb{R}^{m}$, for $x \in \mathcal{D}$ and $i \in[n]$.

## Learning graphs [Belovs'11]

A learning graph $\mathcal{G}$ for $f: \mathcal{D} \rightarrow\{0,1\}$ with $\mathcal{D} \subseteq[d]^{n}$ is

- rooted, weighted and directed acyclic graph
- vertices labeled by $S \subseteq[n]$, the root is labeled by $\emptyset$
- An edge is $e=(S, S \cup\{i\})$ for $S \subseteq[n]$ and $i \notin S$

We must specify

- For every edge $e$ its weight $w(e) \in \mathbb{R}^{+}$
- For every input $y \in f^{-1}(1)$ a unit flow from the root $\emptyset$, where all sinks are labeled by sets $S$ containing a 1-certificate for $y$. The flow through edge $e$ on $y$ is denoted $p_{y}(e)$

We can also authorize edges $e=\left(S, S \cup S^{\prime}\right)$ for $S \cap S^{\prime}=\emptyset$
Then by definition the length $\ell(e)$ of the edge $e$ is $\left|S^{\prime}\right|$

## Learning graph for the OR function

Unit flow for the positive input $x=0 \ldots 010 \ldots 0$, where $x_{i}=1$.


## LEARNing GRAPhS

Learning graph complexity $\mathcal{L G}(f)$ of $f$

- Negative complexity of $\mathcal{G}$ :

$$
C_{0}(\mathcal{G})=\sum_{e \in \mathcal{G}} \ell(e) w(e)
$$

- Positive complexity of $\mathcal{G}$ :

$$
C_{1}(\mathcal{G})=\max _{y \in f^{-1}(1)}\left(\sum_{e \in \mathcal{G}} \ell(e) \frac{p_{y}(e)^{2}}{w(e)}\right) .
$$

- Complexity of $\mathcal{G}: C(\mathcal{G})=\sqrt{C_{0}(\mathcal{G}) C_{1}(\mathcal{G})}$.
- $\mathcal{L G}(f)=\min C(\mathcal{G})$ where $\mathcal{G}$ is a learning graph for $f$


## Learning graph for the OR function



$$
C_{0}(\mathcal{G})=n \quad C_{1}(\mathcal{G})=1 \quad C(\mathcal{G})=\sqrt{n} \quad \mathcal{L G}(\mathrm{OR})=O(\sqrt{n})
$$

## Learning graph is a Relaxation

Theorem[Belovs'11]: $Q(f) \leq \mathcal{L G}(f)$.
Proof Let $E_{i}=\{e=(S, S \cup\{i\}): i \notin S\}$;

$$
\begin{aligned}
& u_{x, i}=\sum_{e \in E_{i}} \sqrt{w(e)}|S\rangle\left|x_{S}\right\rangle \text { for } f(x)=0 \\
& u_{y, i}=\sum_{e \in E_{i}} \frac{p_{y}(e)}{\sqrt{w(e)}}|S\rangle\left|y_{S}\right\rangle \quad \text { for } \quad f(y)=1
\end{aligned}
$$

Then $\sum_{i: x_{i} \neq y_{i}}\left\langle u_{x, i} \mid u_{y, i}\right\rangle$ is the flow through the cut

$$
(\{S: S \subseteq I\},\{S: I \subsetneq S\})
$$

where $\quad I=\left\{i: x_{i}=y_{i}\right\}$

## LEARNING GRAPH IN STAGES



Fact: Complexity of constant stages $=$ sum of the complexities

## Complexity of a stage

$$
\begin{gathered}
\ell(e)=\ell \\
w(e)=1
\end{gathered}
$$



Complexity $=\ell \sqrt{\frac{|V|}{|W|}} \sqrt{\frac{d^{+}}{g^{+}}}$

$$
\frac{|V|}{|W|}=\text { vertex ratio }
$$

$\frac{d+}{g+}=$ out-degree ratio
$W \subseteq V$

## SEVERAL STAGES

$$
C_{i}=\ell_{i} \sqrt{\frac{\left|V_{i}\right|}{\left|W_{i}\right|}} \sqrt{\frac{d_{i}^{+}}{g_{i}^{+}}}
$$

The out-degre ratio is local to the stage, but the vertex ratio depends on the past

Evolution of the vertex ratio with constant in-degrees $d^{-}$and $g^{-}$:

$$
\begin{gathered}
\left|V_{i}\right|=\left|V_{i-1}\right| \frac{d_{i-1}^{+}}{d_{i}^{-}} ; \quad\left|W_{i}\right|=\left|W_{i-1}\right| \frac{g_{i-1}^{+}}{g_{i}^{-}} \\
\frac{\left|V_{i}\right|}{\left|W_{i}\right|}=\left(\frac{\left|V_{i-1}\right|}{\left|W_{i-1}\right|} \times \frac{d_{i-1}^{+}}{g_{i-1}^{+}}\right): \frac{d_{i}^{-}}{g_{i}^{-}}
\end{gathered}
$$

The in-degree ratio $\frac{d_{i}^{-}}{g_{i}^{-}}$decreases the complexity
It depends on some well chosen database

## Example: Element distinctness

Element Distinctness
Oracle Input: A function $f:[n] \rightarrow[n]$.
Question: Is there a pair of distinct elements $i, j \in[n]$ such that $f(i)=f(j)$ ?

For every positive instance $f$ we fix $a \neq b$ such that $f(a)=f(b)$.

## Complexity of ED

$$
V_{i}=\left\{U_{i} \subseteq[n]: \ldots\right\}
$$

$$
U_{1}=\emptyset \quad\left|U_{2}\right|=r \quad\left|U_{3}\right|=r+1 \quad\left|U_{4}\right|=r+2
$$



Vertex ratio at stage 3: $\frac{\left|V_{2}\right|}{\left|W_{2}\right|}=1 ; \quad \frac{\left|V_{3}\right|}{\left|W_{3}\right|}=\frac{d_{2}^{+}}{g_{2}^{+}}: \frac{d_{3}^{-}}{g_{3}^{-}}=\frac{n}{1}: \frac{r}{1}=\frac{n}{r}$
Complexity: $\quad C(\mathcal{G})=C_{1}+C_{3}=r+n / \sqrt{r}=n^{2 / 3}$

## Triangle and Subgraph $H_{H}$

Triangle
Oracle Input: The adjacency matrix $A:\binom{n}{2} \rightarrow\{0,1\}$ of a graph $G$ on vertex set [ $n$ ].
Question: Is there a triangle in $G$ ?

Let $H=([k], E(H))$ be some fixed $k$-vertex graph.
Subgraph $_{H}$
Oracle Input: The adjacency matrix $A:\binom{n}{2} \rightarrow\{0,1\}$ of a graph $G$ on vertex set [ $n$ ].
Question: Is there a copy of $H$ in $G$ ?

## Learning graph based algorithms

[Magniez-Santha-Szegedy'03]: $Q($ TRIANGLE $)=O\left(n^{1.3}\right)$
Database is the complete graph
[Belovs'11]: $Q($ TRIANGLE $)=O\left(n^{35 / 27}\right)=O\left(n^{1.296}\right)$ Sparsification: maintain just a random database where edge slots are chosen with probability $0 \leq s \leq 1$.
[Zhu'11, Lee-Magniez-Santha'11]: $Q\left(\right.$ SuBGRAPH $\left._{H}\right)=O\left(n^{2-2 / k-t}\right)$, where $t=t(k, m, d)>0$. Random database is the union of regular bipartite graphs reflecting the structure of the subgraph
[Belovs'12]: $Q(k$-Distinctness $)=O\left(n^{1-\frac{2^{k-2}}{2^{k}-1}}\right)$
More general learning graph: It depends also on the value of the queried variables

## Our algorithms

- $Q($ TRIANGLE $)=O\left(n^{9 / 7}\right)=O\left(n^{1.285}\right)$
- Generalized algorithm for Subgraph $H_{H}$
- $Q($ Associativity $)=O\left(n^{10 / 7}\right)=O\left(n^{1.428}\right)$


## Triangle: The algorithm

For every positive instance $A$ we fix three vertices $a_{1}, a_{2}, a_{3}$ such that they form a triangle
(1) Setup: Load a complete bipartite graph between $A_{1}$ and $A_{2}$ of respective cardinality $r_{1}=n^{4 / 7}$ and $r_{2}=n^{5 / 7}$
(2) Load $a_{1}$ : Add $a_{1}$ to $A_{1}$ and connect it to all $A_{2}$
(3) Load $a_{2}$ : Add $a_{2}$ to $A_{2}$ and connect it to all $A_{1}$
(4) Load $a_{3}$ : Pick $a_{3}$ and connect it with $\lambda=n^{3 / 7}$ edges to $A_{2}$
(5) Load $\left\{a_{2}, a_{3}\right\}$
(6) Load $\left\{a_{1}, a_{3}\right\}$

Vertex sets in the bipartite graphs database can be unbalanced

## Triangle: The algorithm



## Abstract language for detecting subgraphs

Let $H=([k], E(H))$ be some fixed $k$-vertex graph
Example: 4-PATH


Loading schedule: sequence $S=s_{1} s_{2} \ldots s_{k+m}$ which enumerates all vertices and edges of $H$.
Example: $S=[1,2,4,3,(2,1),(2,3),(3,4), 5,(5,4)]$.
L-graph vertices: regular $k$-partite graphs with classes $A_{1}, \ldots, A_{k}$, and bipartite graphs $E_{i j}$ between $A_{i}$ and $A_{j}$ for $\{i, j\} \in E(H)$.

Parameters: Set sizes $\left\{r_{i}\right\}$ and vertex degrees $\left\{d_{i j}\right\}$
Example: $r_{1}=n, r_{2}=n^{4 / 7}, r_{3}=n^{6 / 7}, r_{4}=n^{5 / 7}, r_{5}=1$; $d_{21}=n^{6 / 7}, d_{23}=n^{6 / 7}, d_{34}=n^{5 / 7}, d_{54}=1$.

## Abstract language for detecting subgraphs

Theorem: There is an explicit function $\phi$ such that

$$
\mathcal{L G}\left(\operatorname{SUBGRAPH}_{H}\right) \leq \phi\left(S,\left\{r_{i}\right\},\left\{d_{i j}\right\}\right)
$$

Example: $\mathcal{L G}(4$-РATH $)=O\left(n^{10 / 7}\right)$
Best parameters can be found by linear programming: https://github.com/troyjlee/learning_graph_lp

Theorem is extendable to:

- $H$ is directed with possible self-loops
- Constant number of 1-certificates instead of just one
- Functions on labeled graphs:

Let $f:[n]^{n \times n} \rightarrow\{0,1\}$ be such that all minimal 1-certificate graphs are isomorphic to a fixed graph $H$. Then

$$
\mathcal{L G}(f) \leq \mathcal{L G}\left(\text { SUBGRAPH }_{H}\right)
$$

## Associativity

Oracle Input: Operation $\circ:[n] \times[n] \rightarrow[n]$
Question: $\exists$ a triple $(a, b, c)$ such that $(a \circ b) \circ c \neq a \circ(b \circ c)$ ?
Grover search: $Q$ (Associativity) $=O\left(n^{3 / 2}\right)$
Theorem: $Q($ Assoc $)=O\left(n^{10 / 7}\right)=O\left(n^{1.428}\right)$


$$
\text { Certificate } \Longleftrightarrow a \circ(b \circ c) \neq(a \circ b) \circ c
$$



Certificate $\Longleftrightarrow\left(a_{2} \circ a_{3}=a_{5}, a_{3} \circ a_{4}=a_{1}\right.$ and $\left.a_{2} \circ a_{1} \neq a_{5} \circ a_{4}\right)$
Certificate graph:

$Q($ Assoc $) \leq \mathcal{L G}($ Assoc $\left.) \leq \mathcal{L G}(4-\mathrm{PATH})=O\left(n^{10 / 7}\right)\right)$

## Conclusion

Recent results:

- [Jeffery, Kothari, Magniez'12]: Can simulate our algorithms by quantum walks
- [Belovs, Rosmanis'12]: Our triangle algorithm is the best non-adaptive learning graph algorithm
Open problems: Complexity of
- Triangle
- Graph Collision
- $k$-Distinctness
- Associativity
- Matrix Product Verification

