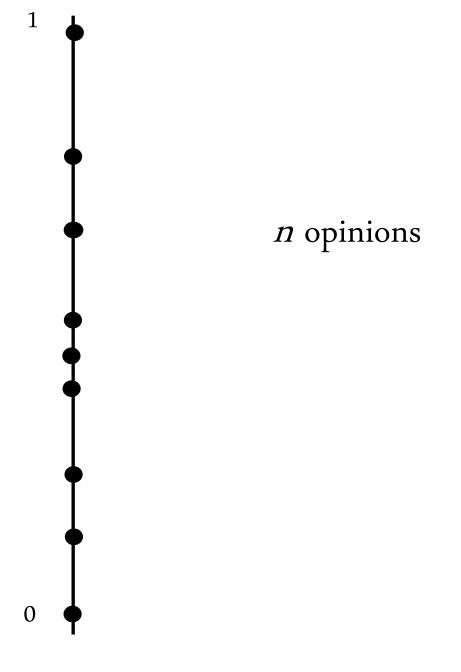
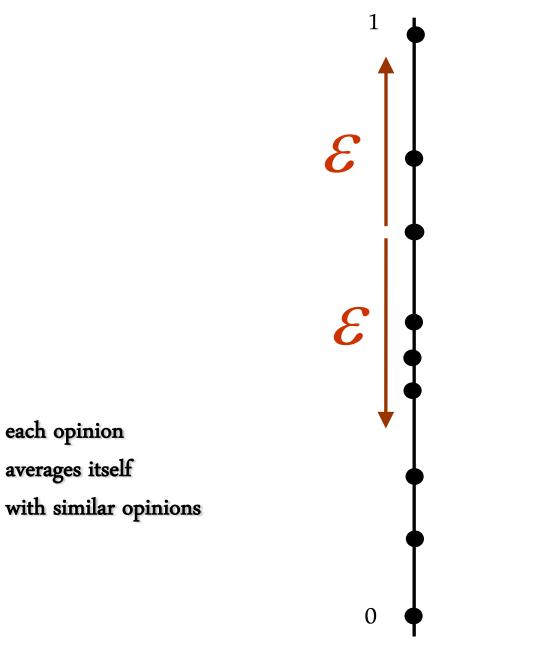
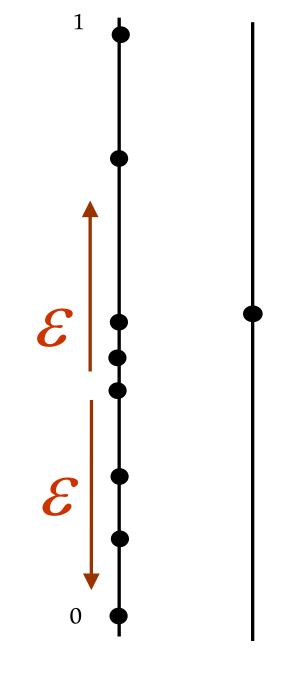
## Analytical Tools for Natural Algorithms

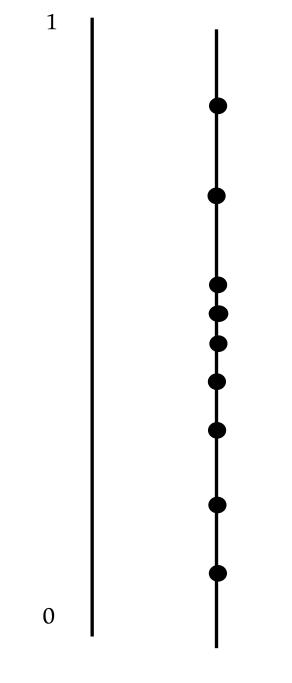
Bernard Chazelle Princeton University three multiagent agreement systems



Hegselmann-Krause opinion dynamics







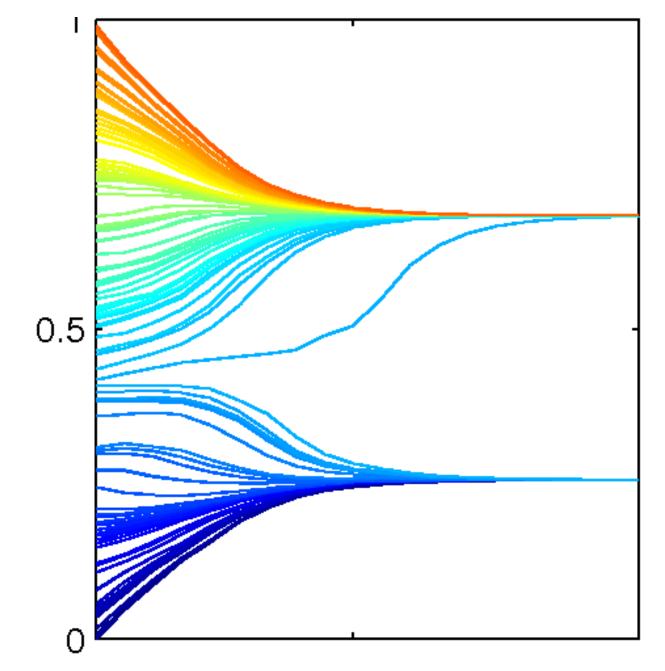
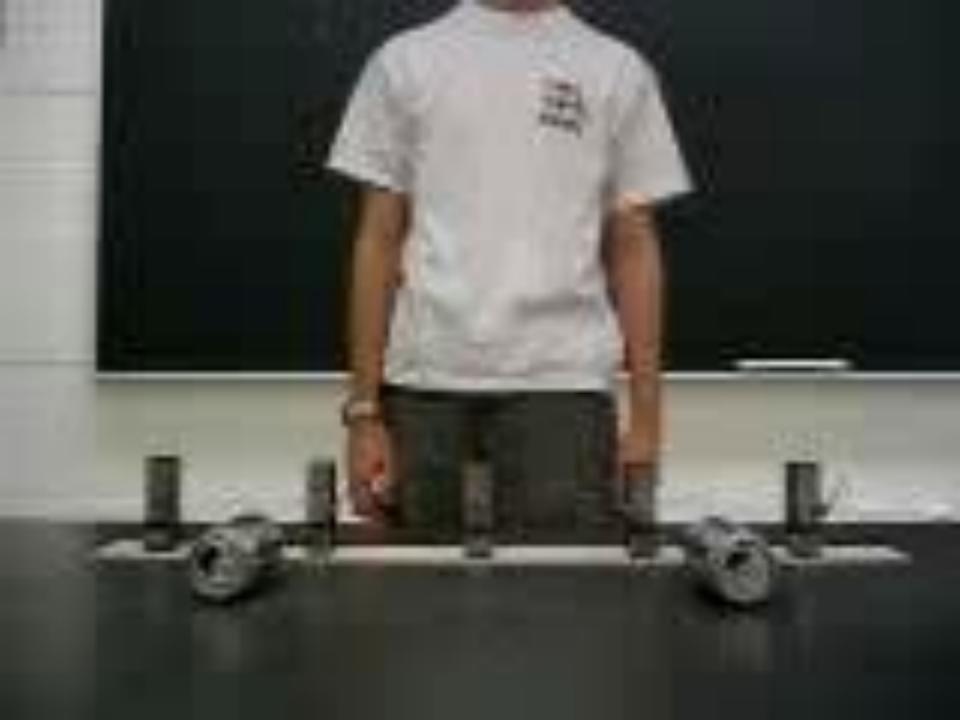


figure by Urbig-Lorenz-Herzberg

?

## Kuramoto sync







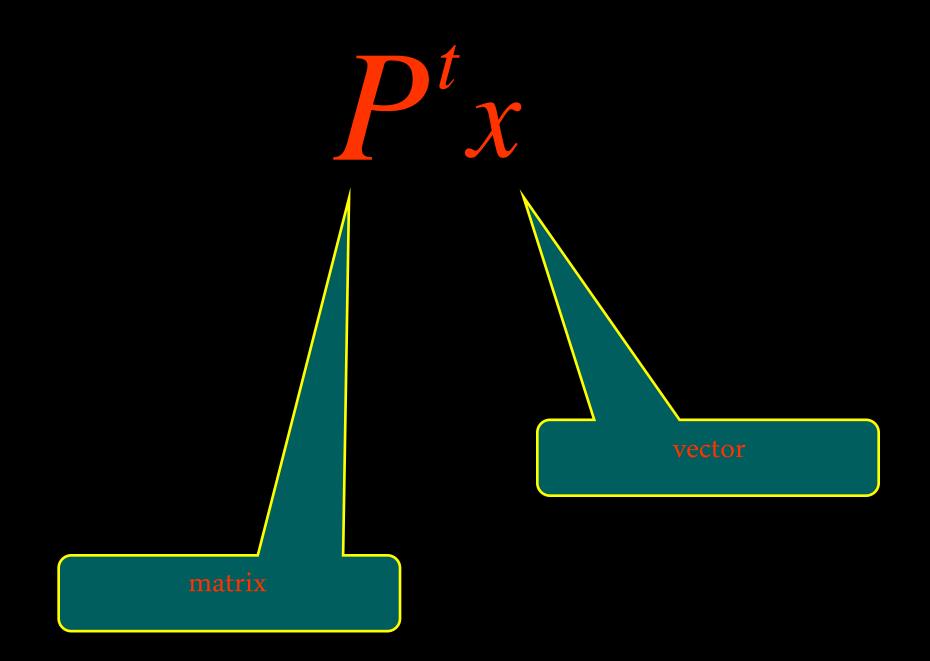
#### all of these dynamical systems converge in time

 $2^{O(n)}$ 

where n is the number of opinions, metronomes, fireflies, etc.

no previous convergence bound was known

let's step back a little





predict behavior for large *t* 





dimension separation

independent 1-dim systems

that was was easy

#### what about?

 $P_t \cdots P_2 P_1 X$ 

where

 $P_{t} = f(x, P_{1}, \cdots, P_{t-1})$ 

nonlinear dynamics



## hopeless

### attack

# $P_t \cdots P_2 P_1 X$

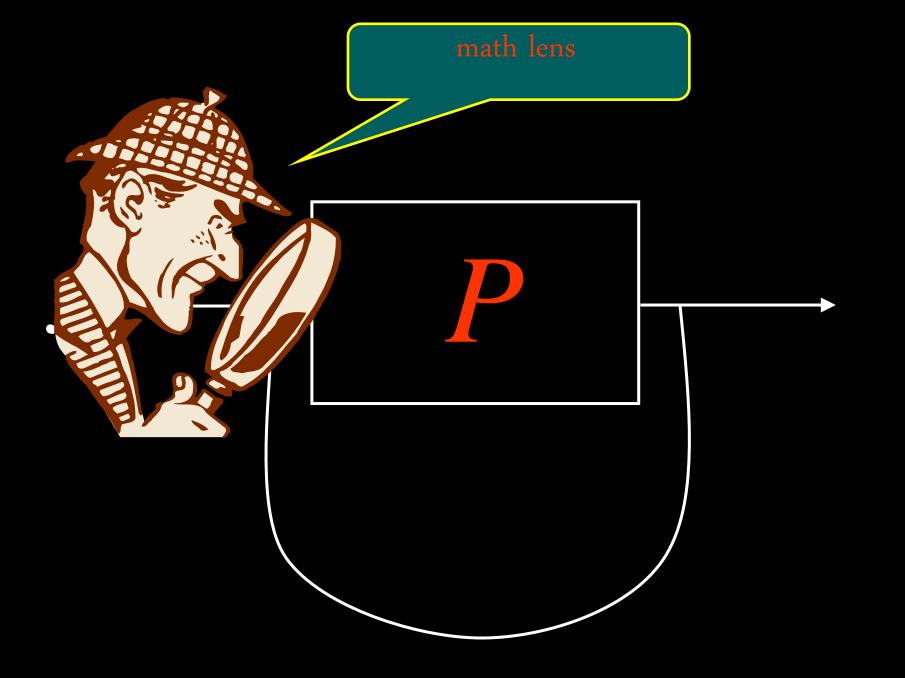
as

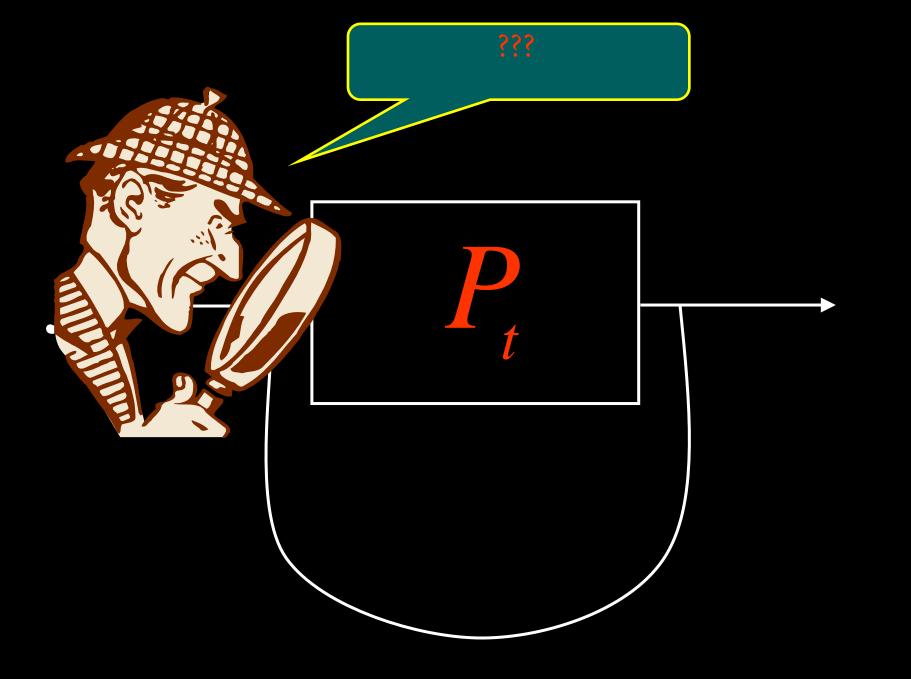
 $P_t(\cdots(P_2(P_1x)))$ 

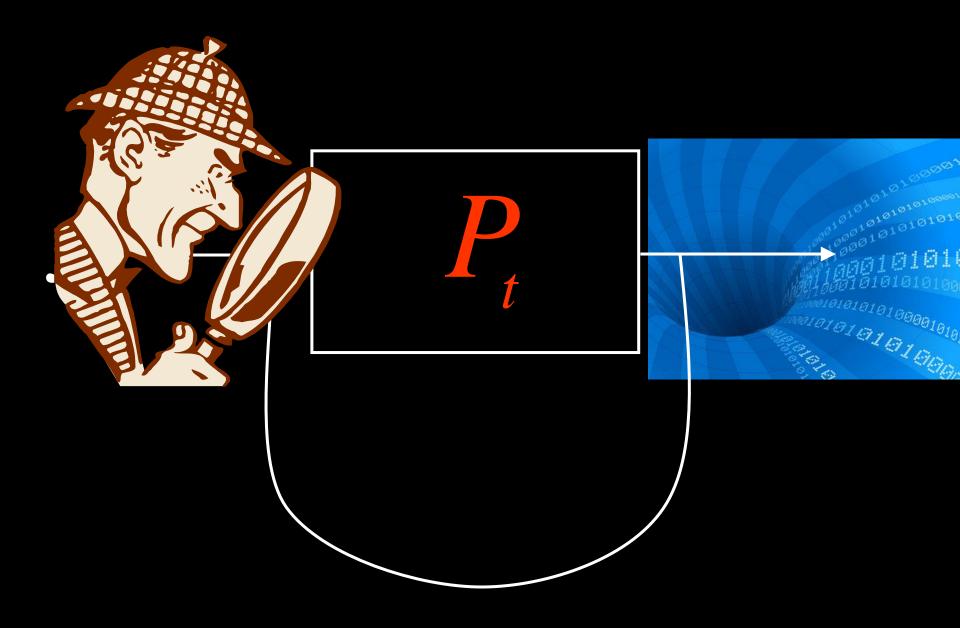
bye-bye old math

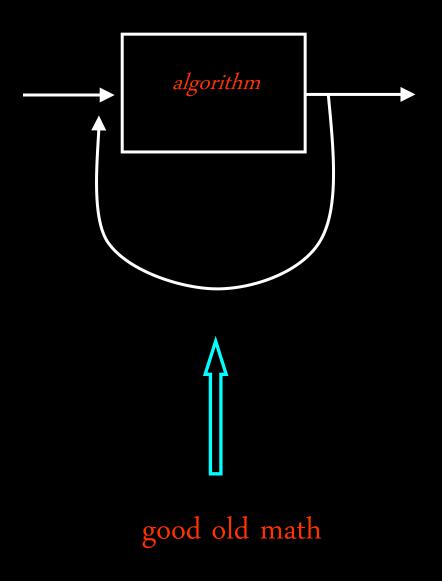
hello data analysis classification machine learning statistics

$$\frac{\partial \Theta}{\partial \theta} \operatorname{MT}(\xi) = \frac{\partial}{\partial \theta} \int_{\mathbb{R}_{n}}^{T} (x) f(x, \theta) dx = \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \frac{1}{f(x)} dx = \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \frac{1}{f(x)} dx = \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \frac{1}{f(x)} dx = \int_{\mathbb{R}_{n}}^{T} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} (x) \cdot \frac{\partial}{\partial \theta} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} (x) \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} f(x) \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} f(x) \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} f(x) \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}_{n}}^{T} \int_{\mathbb{R}_{n}}^{\frac{\partial}{\partial \theta}} \int_{\mathbb{R}$$

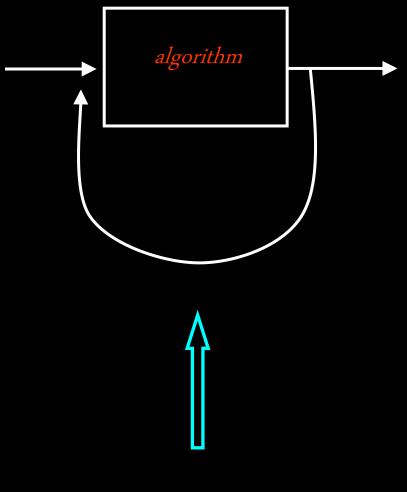








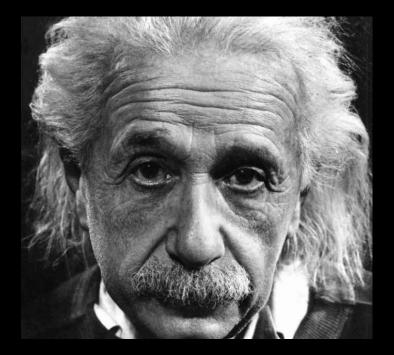
rarely works



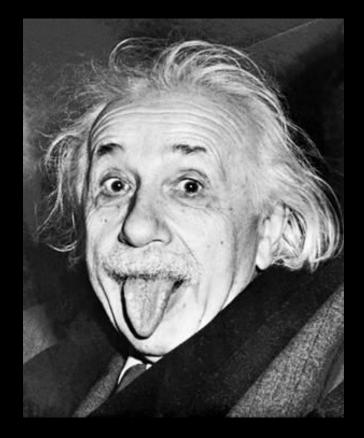
data analysis

works if you redefine the meaning of "works"

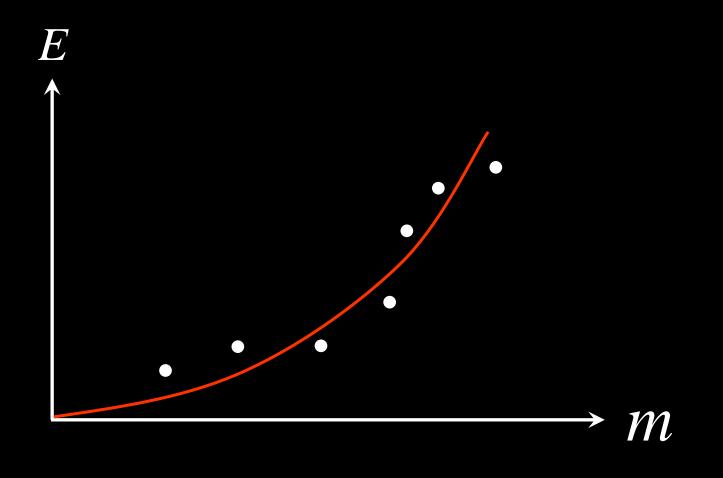
relativity theory



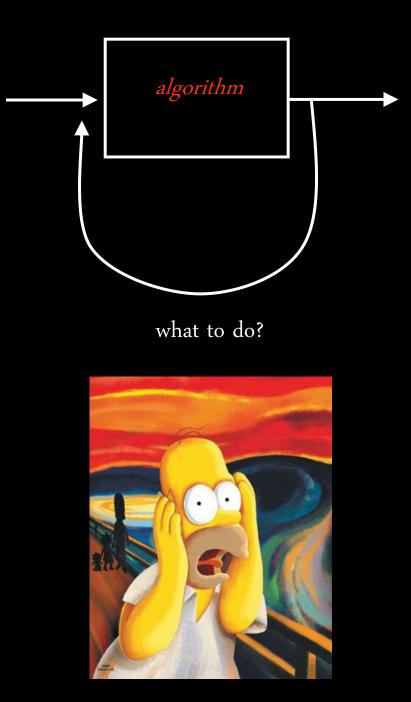
relativity theory via data analysis

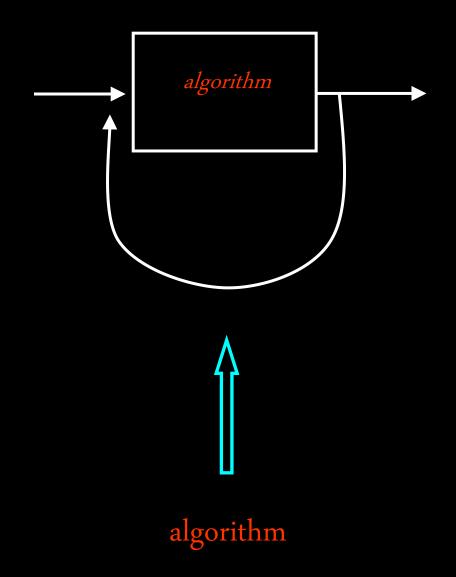


relativity theory via data analysis



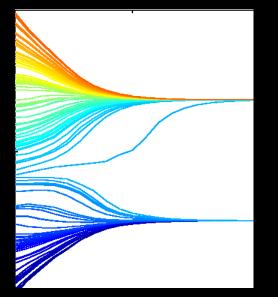
 $E = m^{0.92} c^{2.03}$ 

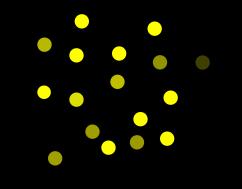




use algorithms to analyze algorithms

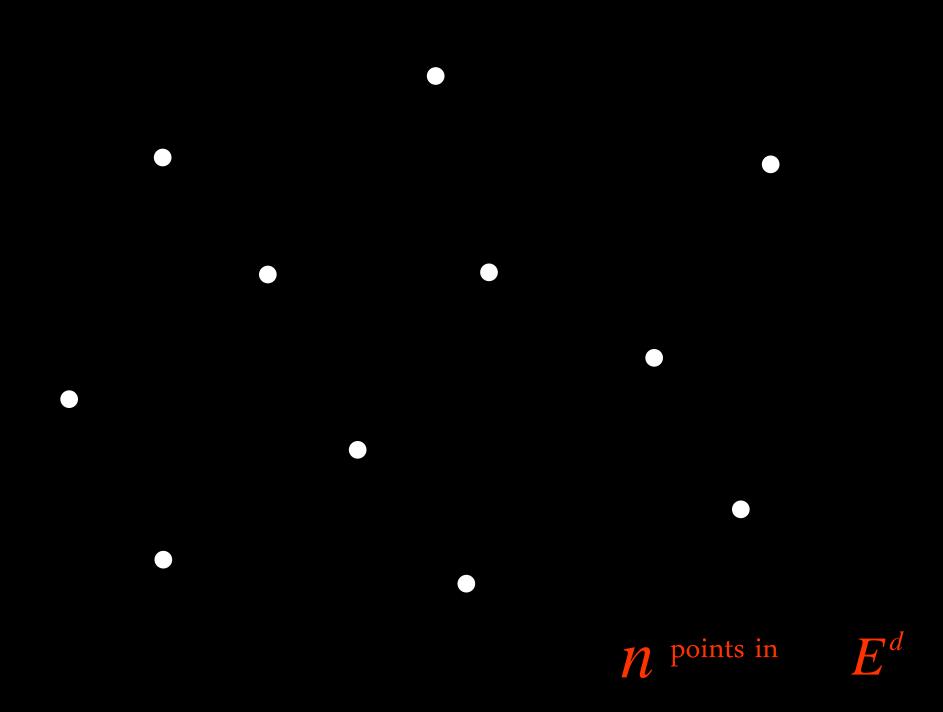
## back to our 3 agreement systems

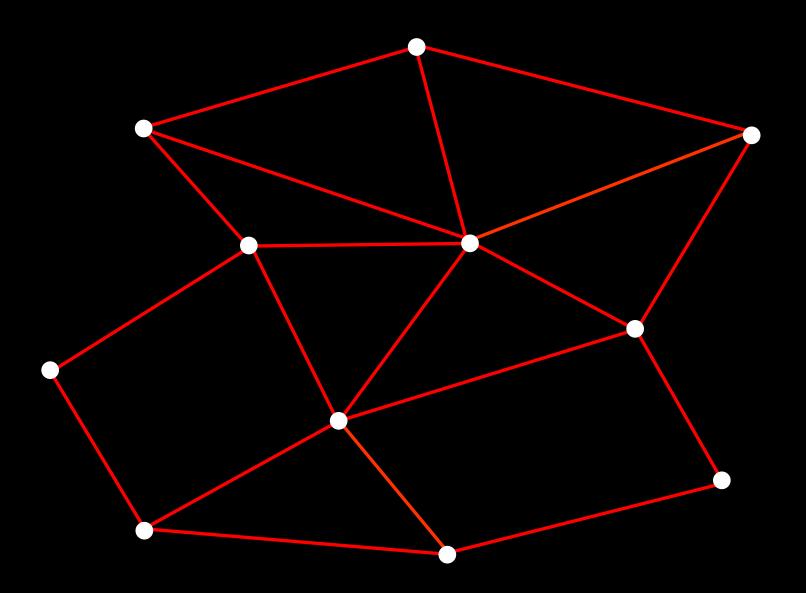




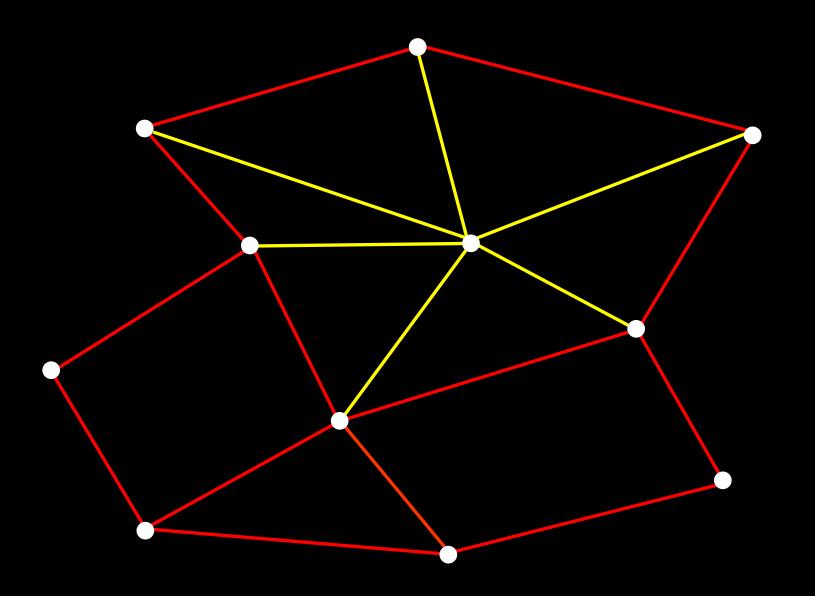


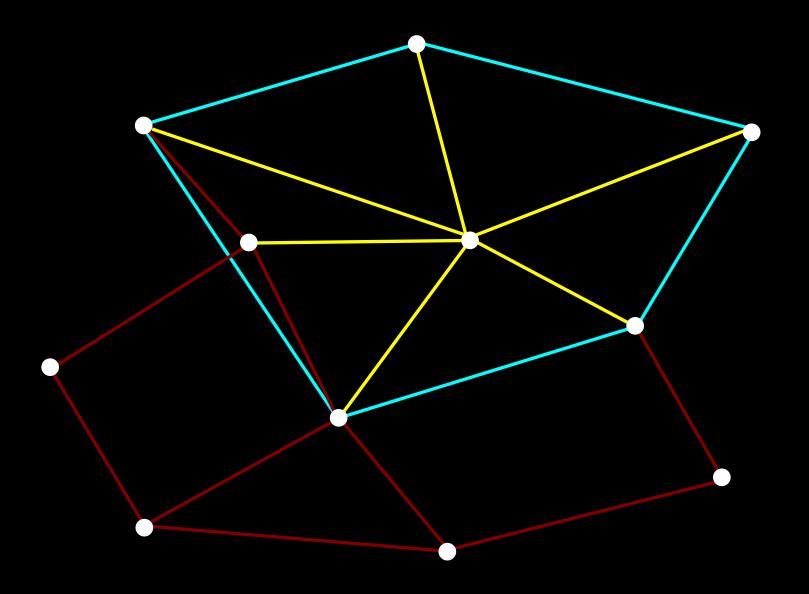
a common geometric framework

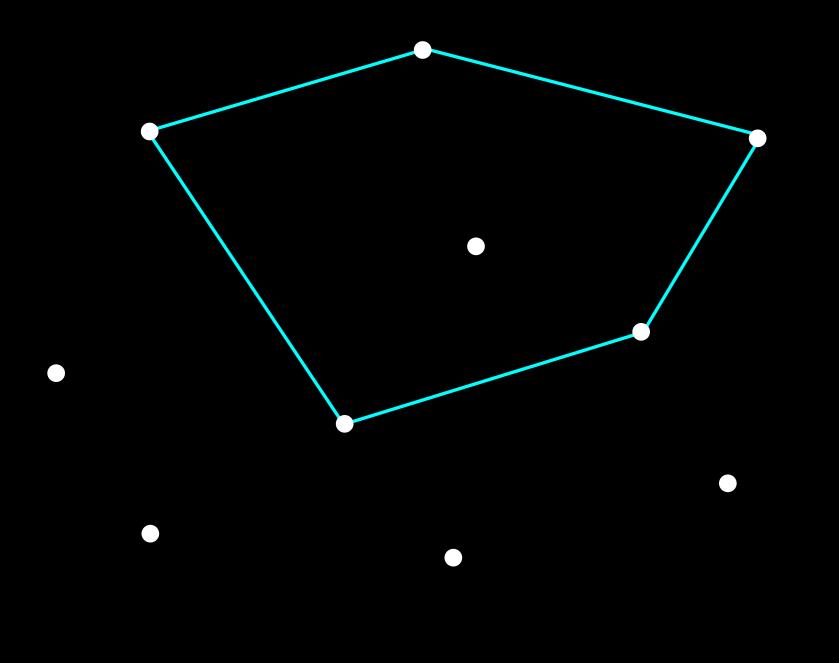


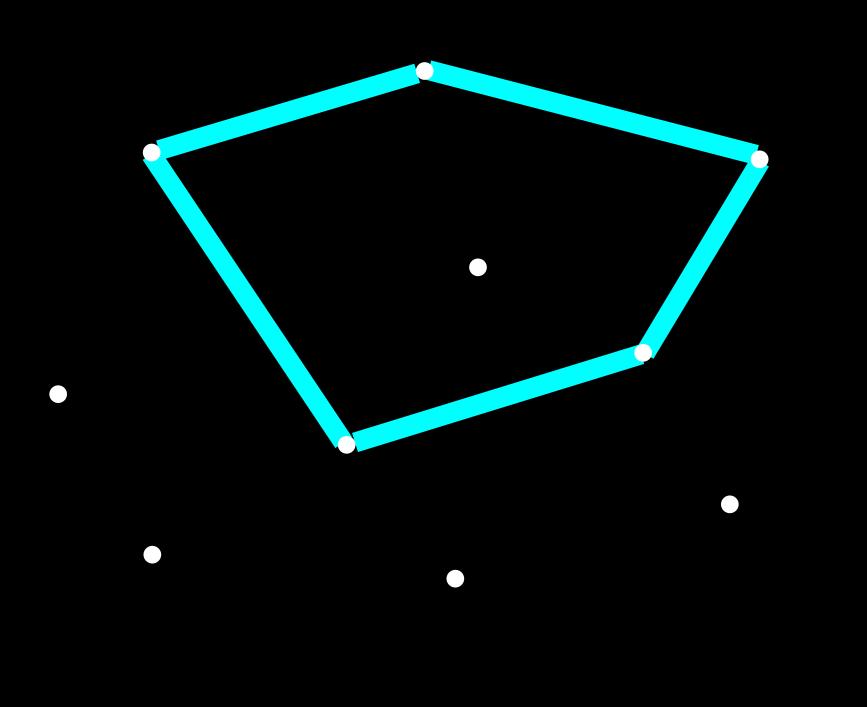


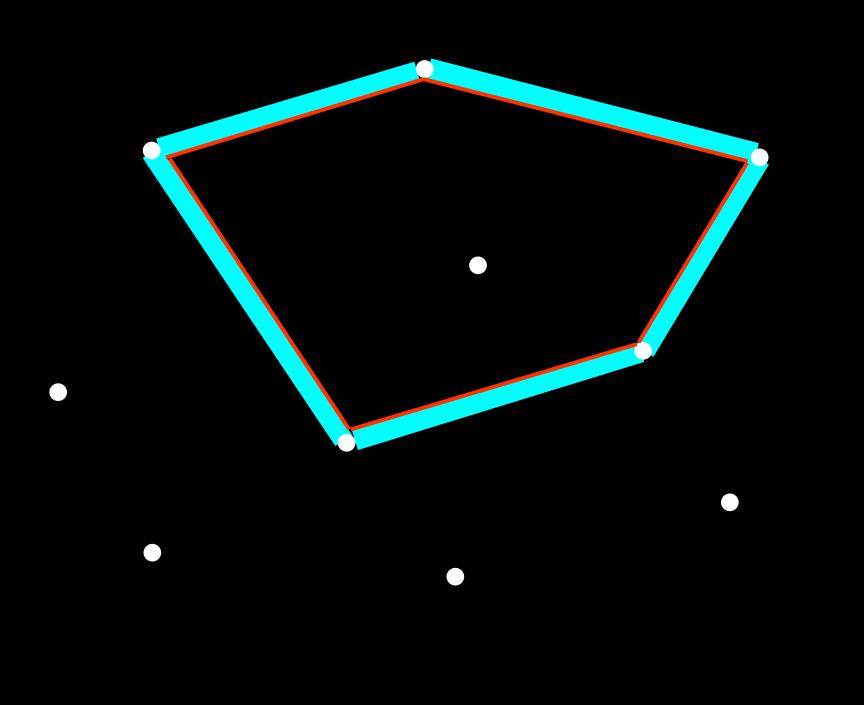
infinite graph sequence

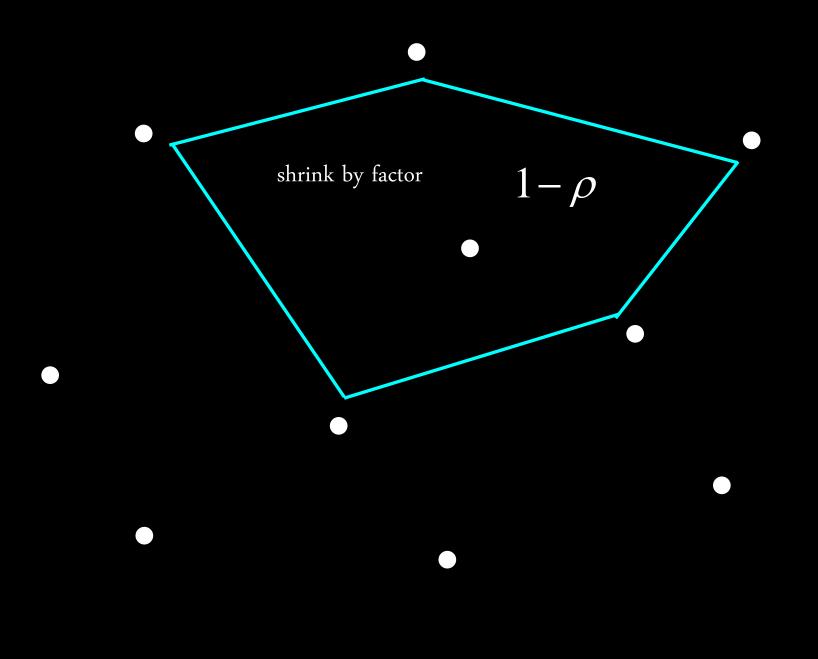


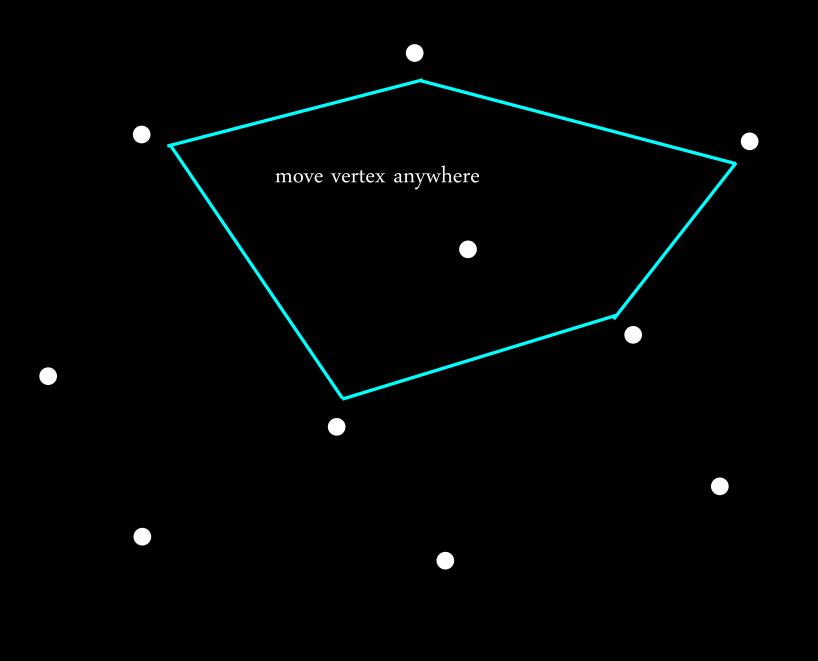


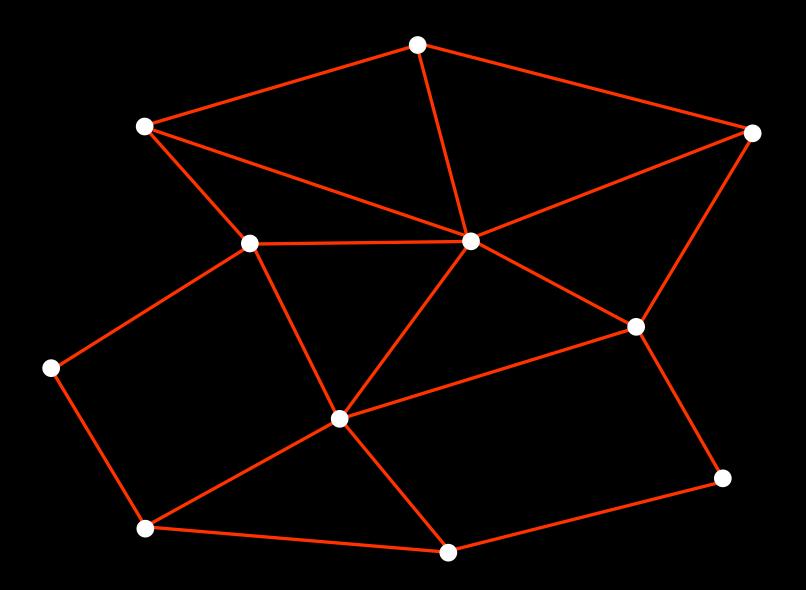




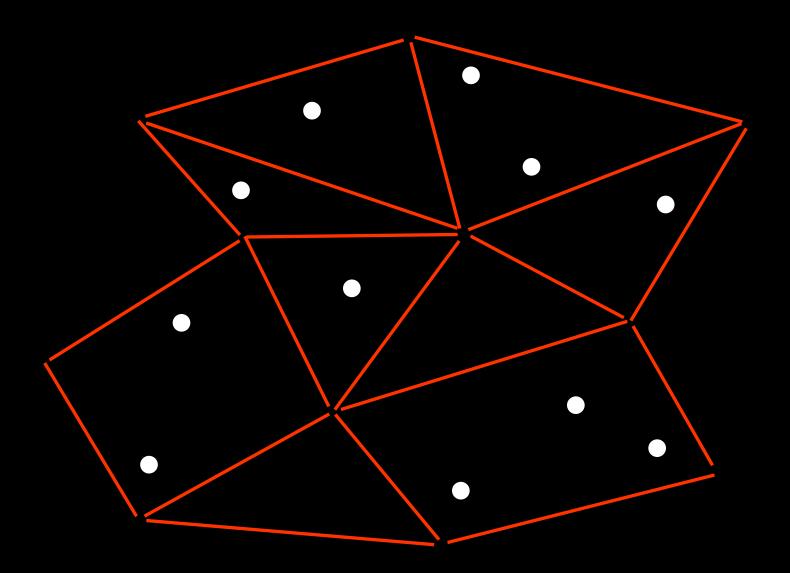






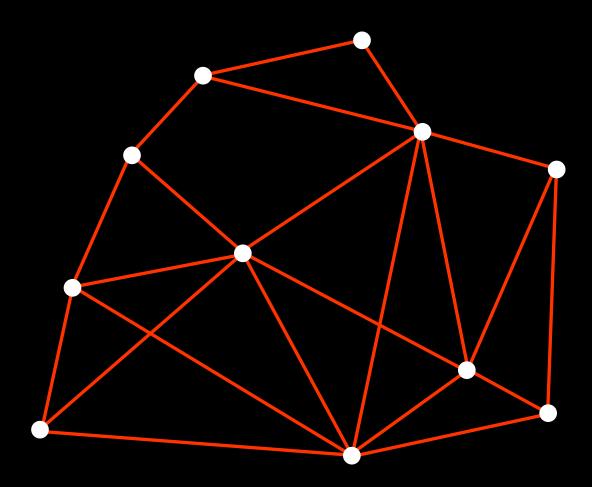


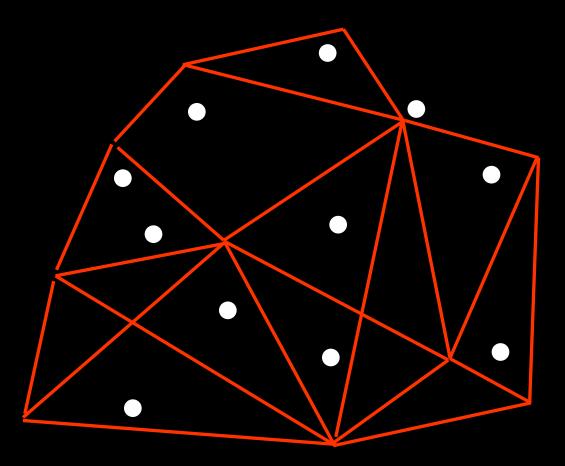
repeat for each node



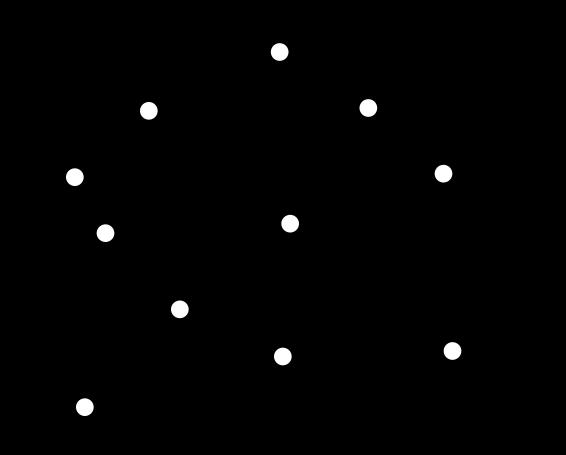
( )( )( )

get second graph





move all the vertices

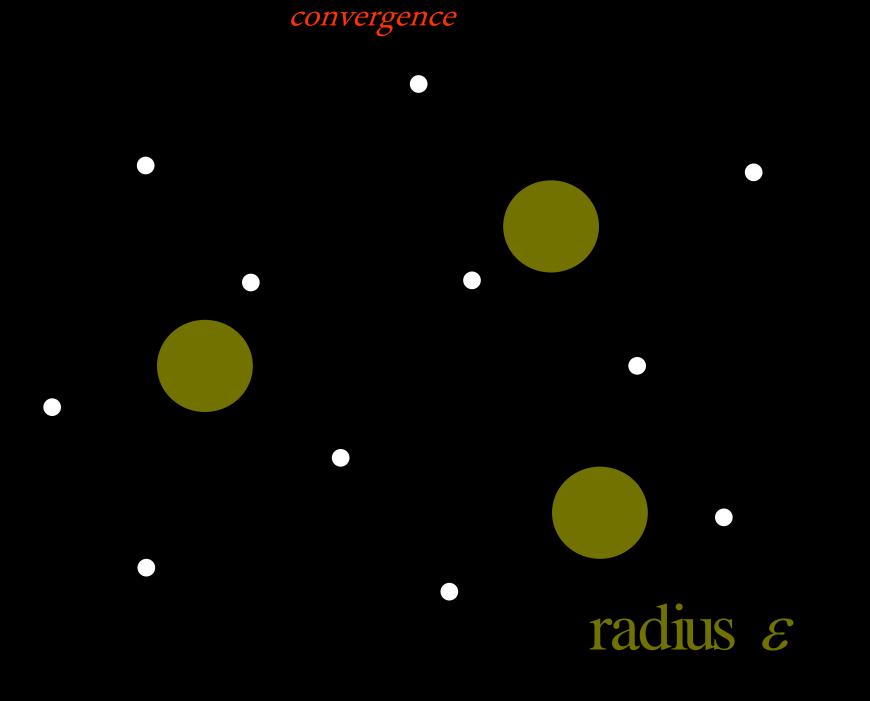


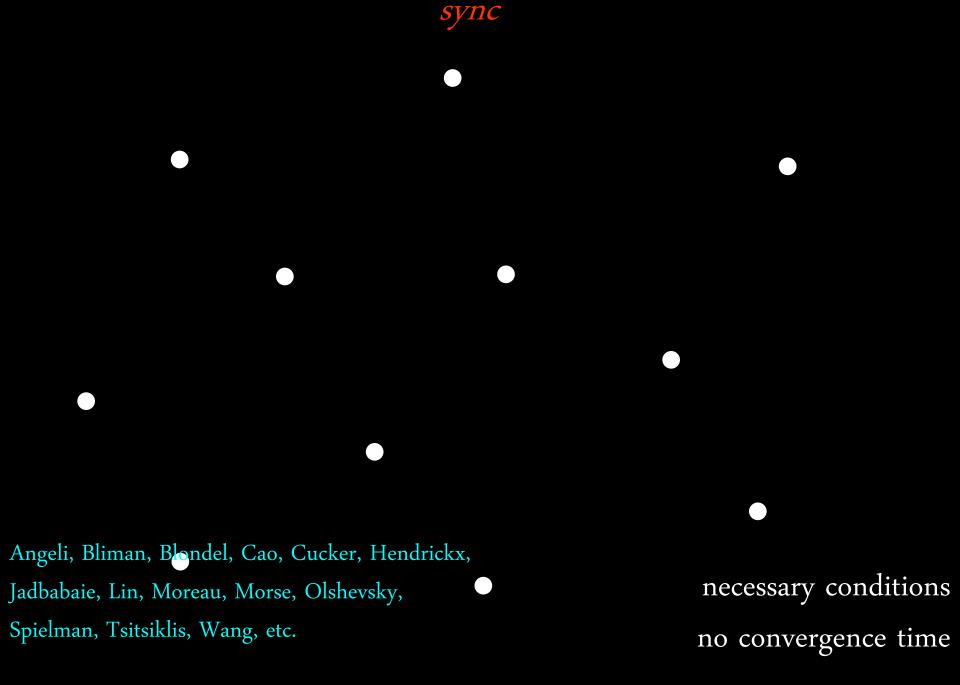
get 3<sup>rd</sup> graph, move vertices, repeat...

adversary chooses all graphs and all moves nondeterministically

does this thing always converge?









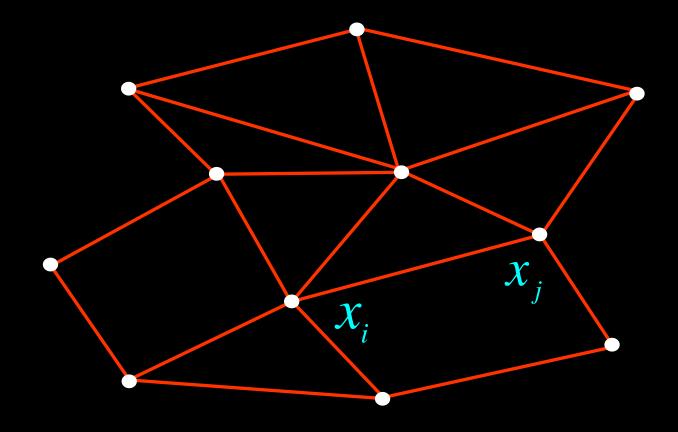
### System always converges :

### (i) number of moves is infinite

### (ii) number of nontrivial moves

$$\leq \min \left\{ \varepsilon^{-1} \rho^{-O(n)}, (\log 1/\varepsilon)^{n-1} \rho^{-n^2(1+o(1))} \right\}$$

### main tool total s-energy



# $E(s) = \sum_{t} \sum_{(i,j)\in G_t} \|x_i - x_j\|_2^s$



### Dirichlet series $\rightarrow$ inverse formula (Mellin transform) $\rightarrow$ lossless encoding

Does it ever converge?

E(s)

## converges for all S > 0

### • analytic for $\Re s > 0$

### • pole at s = 0 of order n-1

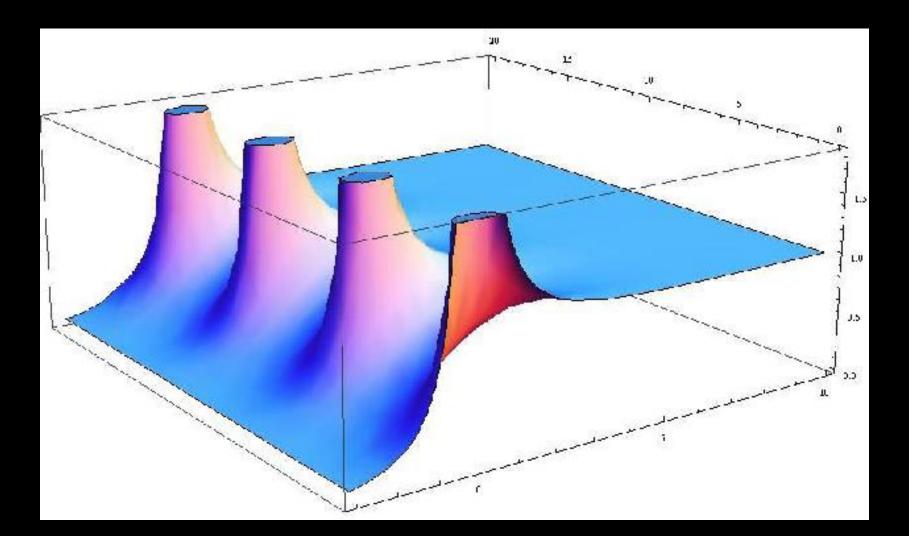
E(s)

### in general, no analytic continuation over whole plane

#### conjecture

for any *n*, max E(s) has analytic continuation with discrete poles at *s*=0

# true for n = 2





$$E(S) \leq \begin{cases} \rho^{-O(n)} & \text{if } s = 1 \\ \\ S^{n-1}\rho^{-n^2(1+o(1))} & \text{if } s < 1 \end{cases}$$

proof algorithmicized proofs of old math flow algorithm recurrences, etc.



Schur's Lemma

*Every square matrix is unitarily similar to a triangular matrix* 

#### Unitary equivalence and normal matrices

of C\*. Apply the Gram-Schmidt orthonormalization procedure mad to this basis to produce an orthonormal basis

of C". Array these orthonormal vectors left to right as the column of unitary matrix  $U_1$ . Since the first column of  $AU_2$  is  $\lambda_1 x^{(0)}$ , a calculate reveals that  $U_1^*(AU_1)$  has the form

$$U_{1}^{*}AU_{2} = \begin{bmatrix} -\frac{\lambda_{2}}{0} & \bullet \\ \bullet & \downarrow & A_{2} \end{bmatrix}$$

The matrix  $A_1 \in M_{n-1}$  has eigenvalues  $\lambda_2, ..., \lambda_n$ . Let  $x^{1/2} \in \mathbb{C}^{n-1}$  by normalized eigenvector of  $A_1$  corresponding to  $\lambda_2$ , and do it all or again. Determine a unitary  $U_2 \in M_{n-1}$  such that

$$U_2^*\mathcal{A}_1U_2 = \left[\begin{array}{c|c} \lambda_2 & \vdots & \bullet \\ \hline 0 & \vdots & A_2 \end{array}\right]$$

and ler

20

$$V_{2} \approx \left[ \begin{array}{c} 1 \\ 0 \end{array} \middle| \begin{array}{c} 0 \\ U_{2} \end{array} \right]$$

The matrices  $V_2$  and  $U_1V_2$  are then unitary, and  $V_2^*U_1^*AU_2V_2$  has the form

$$V_2^* U_1^* A U_1 V_2 = \begin{bmatrix} \lambda_1 & * & \\ 0 & \lambda_2 & * \\ 0 & A_2 & \end{bmatrix}$$

ontinue this reduction to produce unitary matrices  $U_i \in M_{n-1+1}$ , is ...., N = 1 and unitary matrices  $V_i \in M_{i+1} = 2$ . The matrix

$$U = U_1 V_2 V_1 \dots V_n$$

unitary and U\*AU yields the desired form.

If all eigenvalues of  $A \in M_{*}(\mathbb{R})$  happen to be real, then the correanding eigenvectors can be chosen to be real and all the above stepwhe carried out in real arithmetic, verifying the final assertion. Remark: Follow the proof of (2.3.1) to see that "upper triangular" dd be replaced by "lower triangular" in the statement of the theorem b, of course, a different unitary equivalence U.

2 Example. Neither the unitary matrix U nor the triangular matrix. Theorem (2.3.1) is unique. Not only may the diagonal entries of T

#### 2.5 Schue's unitary triangularization theorem

ate cionvalues of (4) appear in any order, but unitarily equivalent upp magniat matrices may appear very different above the diagonal. I asampte.

	11	1.	-47			2	-1	3/2
	0	2	2	and	$T_2 \approx$	0	1	√2
			3					3

are mitarily equivalent via

	1	1	0	1
11=-1-	I	-1	0	
126.	0	0	v2	

In general, many different upper triangular matrices can be in the same mitary equivalence class.

Remark: Notice that the technique of the proof (2.3.1) is simply the of sequential deflation, as outlined in Problem 8 in Section (1.4).

Foreige, If A c Ma is unitarily equivalent to an upper triangular man  $T = [t_i] \in M_{s_i}$  the entries  $t_{ij}$  are not uniquely determined, but the quarter try  $\sum_{i=1}^{n} |t_{ij}|^2$  is uniquely determined. Determine the value of  $\sum_{i=1}^{n} |t_{ij}|^2$ in forms of the entries and eigenvalues of A. Hint: Use (2.2.2).

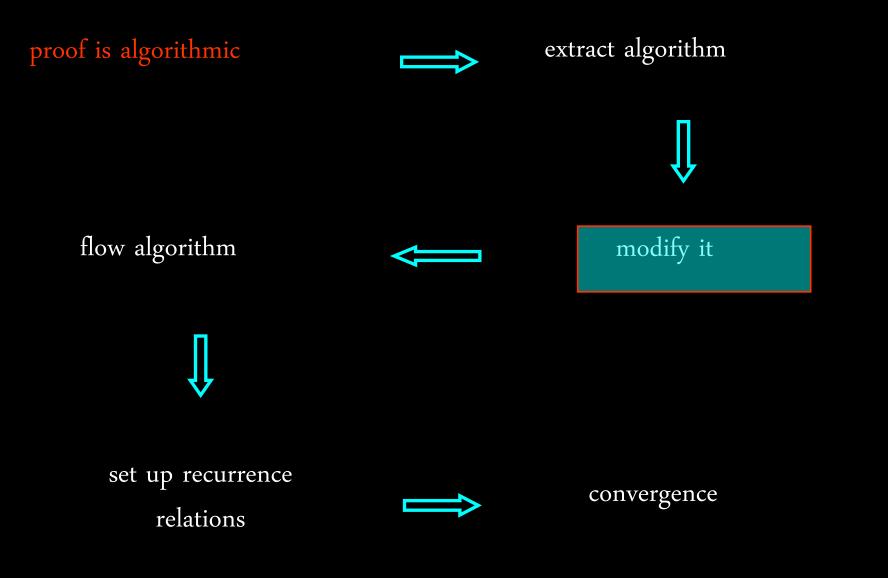
**Exercise.** If  $A = \{a_{ij}\}$  and  $B = \{b_{ij}\} \in M_2$  are similar and if  $\sum_{i=1}^{n} \|a_{ij}\|^2$ 5. (b, 1, show that A and B are unitarily equivalent. Show by example that this is not the case in higher dimensions. Hint: Notice that if A and are anitarily equivalent, then so are  $A + A^*$  and  $B + B^*$ . Consider

1000	1	3	0]			11	Φ.	0	F
A =	0	2	4	and	B =	0	2	.5	Ľ
		0						-3	

It is a useful adjunct to (2.3,1) that a commuting family of matrice may be simultaneously upper triangularized.

23,3 Theorem, I, et  $\Im \subseteq M_n$  be a commuting family. There is a unitar matrix  $U \in M_n$  such that  $U^*AU$  is upper triangular for every  $A \in \mathbb{F}$ .

Proof: Return to the proof of (2.3.1). Exploiting (1.3.17) at each ste of the proof in which a choice of an eigenvector (and unitary matrix is made, the same eigenvector (and unitary matrix) may be chosen for every A e 3, Moreover, unitary equivalence preserves commutativity proof is algorithmic



use algorithms to analyze algorithms



