

# An Analysis of the Chaudhuri and Monteleoni Algorithm

--- a differentially private logistic regression algorithm

Cynthia Dwork, Parikshit Gopalan, Huijia (Rachel) Lin,  
Toniann Pitassi, Guy Rothblum, Adam Smith, Sergey Yekhanin

# Logistic Regression

- Used to predict the probability of an event by learning weights on different attributes. ?

Age	Female	Single	Clicked	Salary
40	1	1	1	10K

Weights:

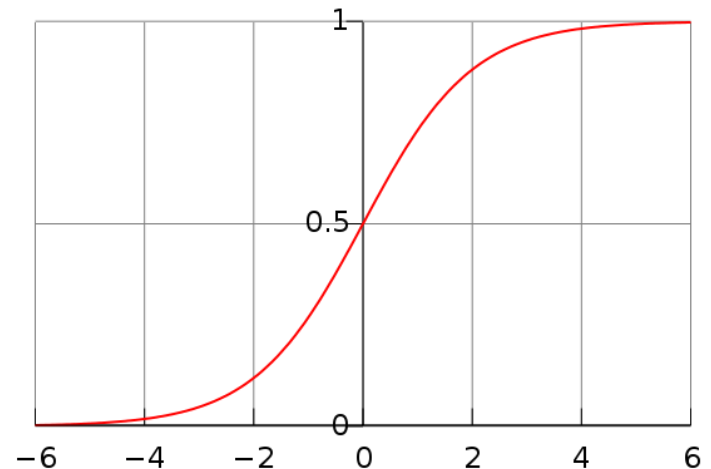
.03	.5	.05	.001	1.5
-----	----	-----	------	-----

Weighted Sum:

$$\begin{aligned} z &= 40*0.03 + 1*0.5 + 1*0.05 \\ &\quad 1*.001 + 10*1.5 \\ &= 27.551 \end{aligned}$$

$$P = \frac{1}{1 + e^{-z}}$$

Logistic Function



# Logistic Regression

Fit the training data to Logistic Func

For  $(x_i, y_i)$ ,  $w$  predicts:

$$\text{w.p } P_i(1) = \frac{1}{1 + e^{-\langle w, x_i \rangle}} \quad \text{being positive}$$

$$\text{w.p } P_i(-1) = \frac{1}{1 + e^{\langle w, x_i \rangle}} \quad \text{being negative}$$

Maximize the log-likelihood  $\sum_i \log p_i(y_i)$

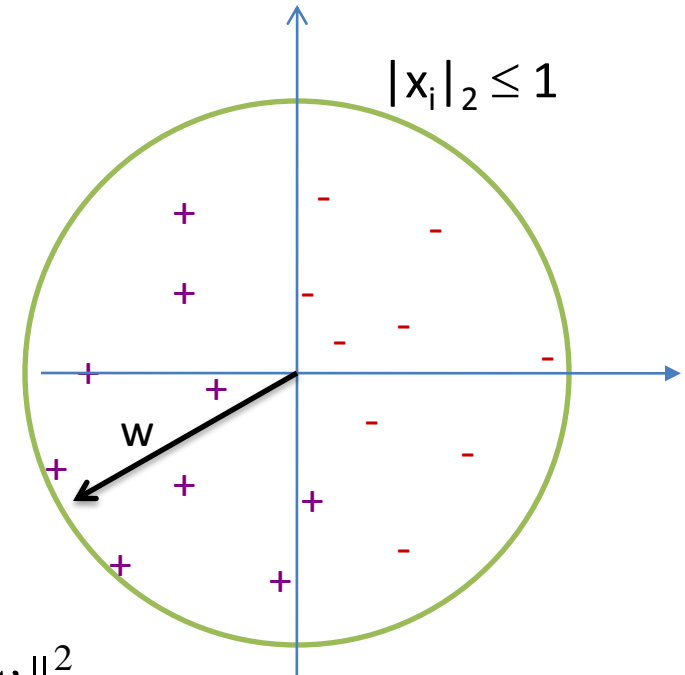
Minimize the log-loss  $\sum_i \log \frac{1}{p_i(y_i)}$

$$L^X(w) = \sum_{ii} \log(1 + e^{-\langle w, x_i \rangle}) + \lambda \|w\|_2^2$$

Widely used in statistics, physics, social science, etc

(attributes, label) =  $(x_i, y_i)$

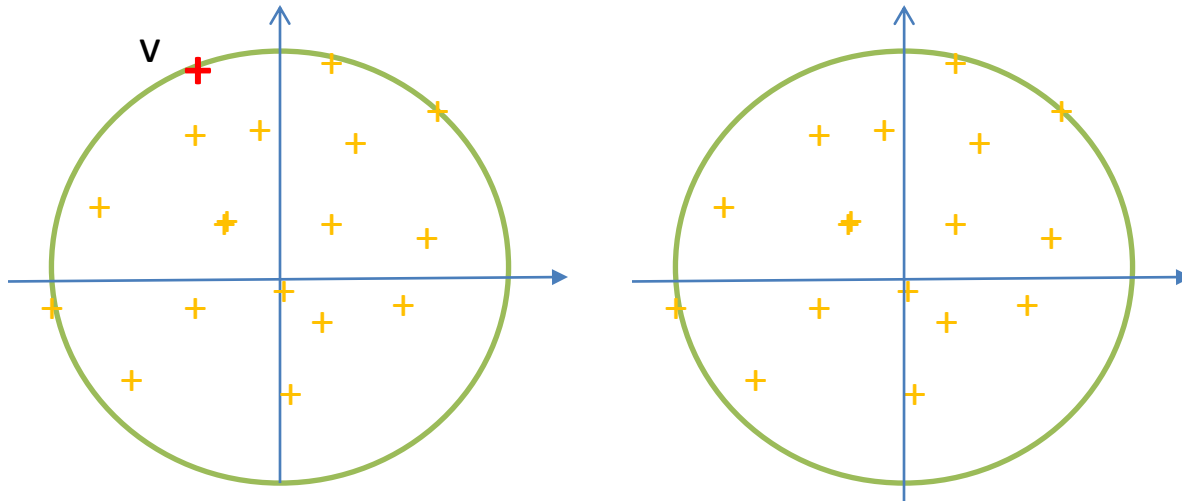
$x_i \in \mathbb{R}^d$   $y_i = 1$  or  $-1$   $i \in [n]$



## Differentially Private

# Logistic Regression

A LR algorithm  $\mathcal{A}$  is  $\epsilon$ -differentially private, if for all neighboring databases  $X$  and  $X'$ ,

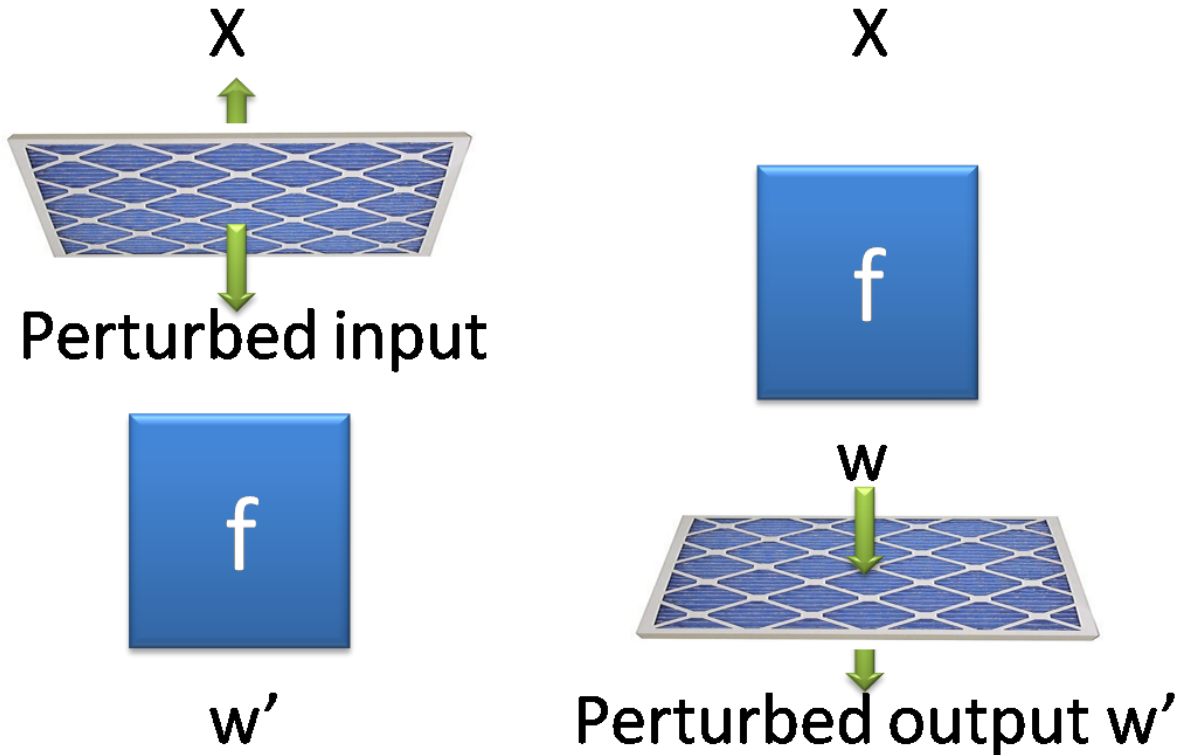


for all set of  $w, W$

$$\Pr[\mathcal{A}(X) \in W] < e^\epsilon \Pr[\mathcal{A}(X') \in W]$$

The behavior of the algorithm is “unchanged” no matter if a data point opts in or opts out.

# Differentially Private LR

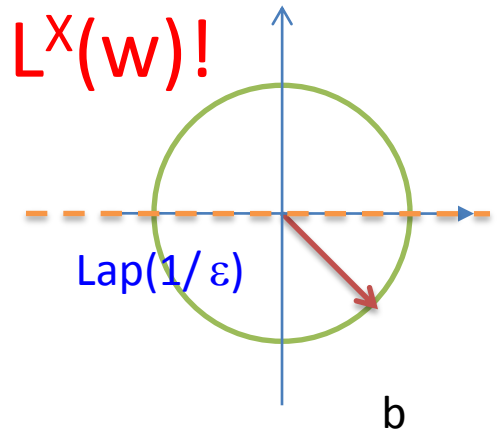


Gradient Descent [FM] Add noise prop. to GS  
 $GS(LR) \leq 2/\lambda$  [CM]

# Algorithm [CM]2

## Perturb the Loss Function $L^X(w)$ !

- Draw noise vector  $b$  w.p  $p(b) \propto e^{-\varepsilon|b|}$
- Output  $w$  that minimizes

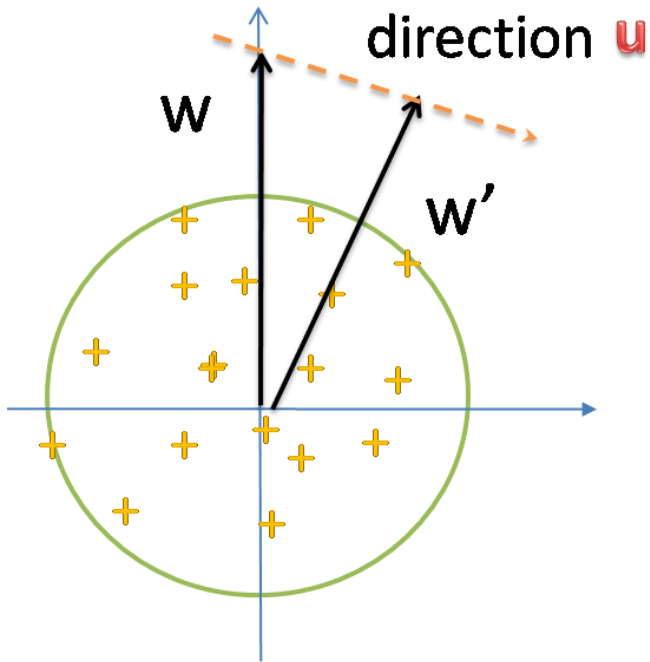


$$L^X(w) + \langle b, w \rangle$$

In [CM], simulation results show that [CM]2 outperforms the approach that adds noise proportional to GS.

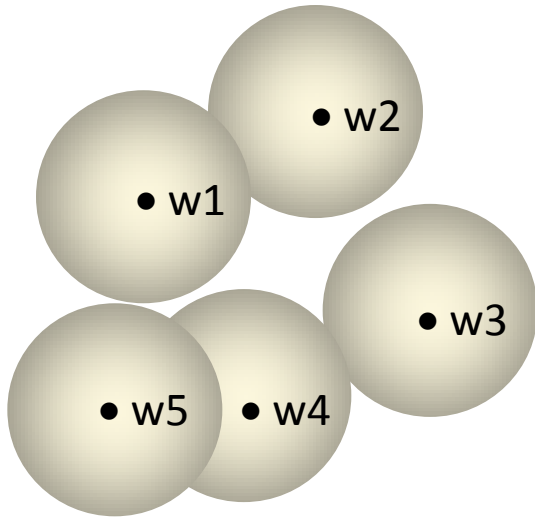
$X$ : data set     $w$ : true optimum     $w'$ : output of [CM]2

$$\text{Noise} = |w' - w| \text{ ???}$$



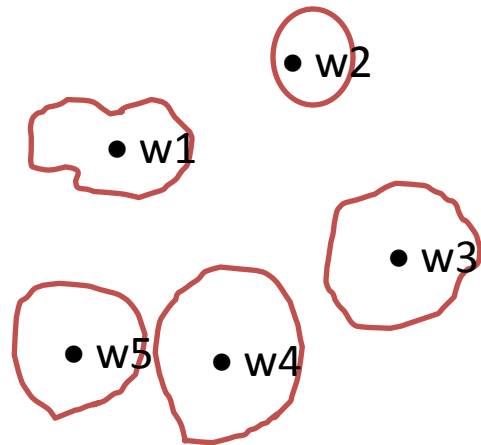
# Sensitivity of Function

$$|\text{Opt}(X) - \text{Opt}(X')|$$

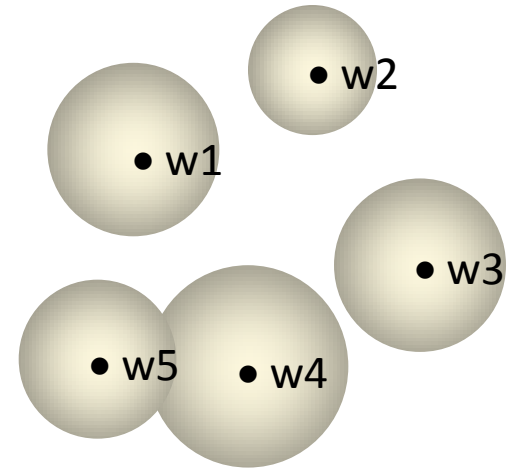


Global sensitivity

However,



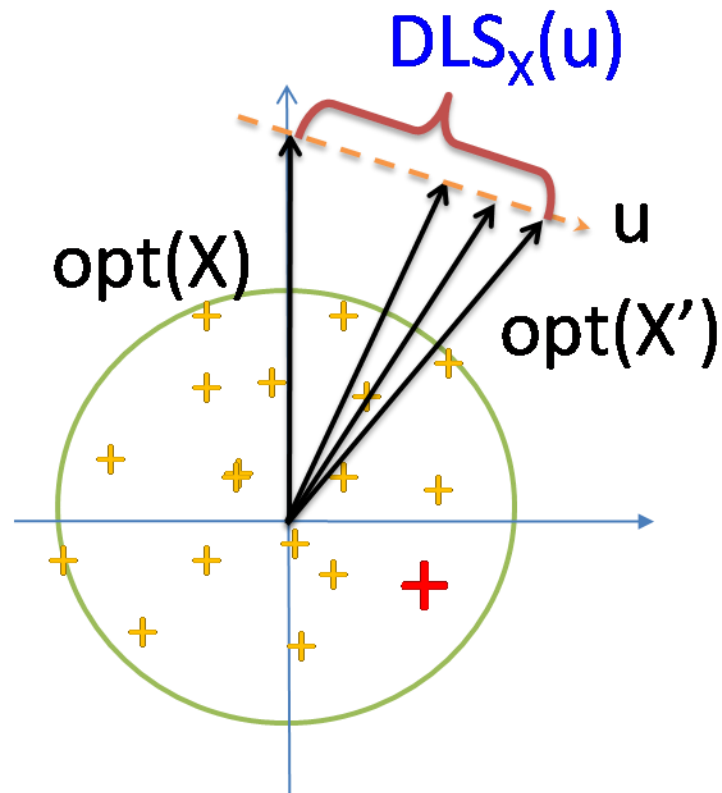
Real Sensitivity



local sensitivity



# Directional Local Sensitivity



$\text{DLS}_X(u)$  is the supremum of  
 $|\text{opt}(X') - \text{opt}(X)|$

over all neighboring data sets  $X'$ , s.t.  
 $\text{opt}(X') - \text{opt}(X)$  is parallel to  $u$ .

$$\text{DLS}_X(u) \leq e/T_X(u) *$$

# Summary

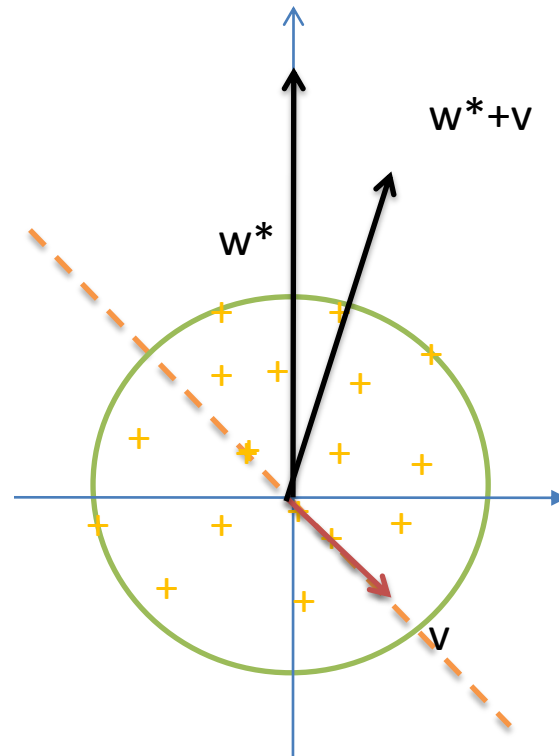
- Analysis of the CM2 algorithm.
- Directional local sensitivity.

Is the CM2 algorithm actually “tracing” DLS?

# Algorithm [CM]1

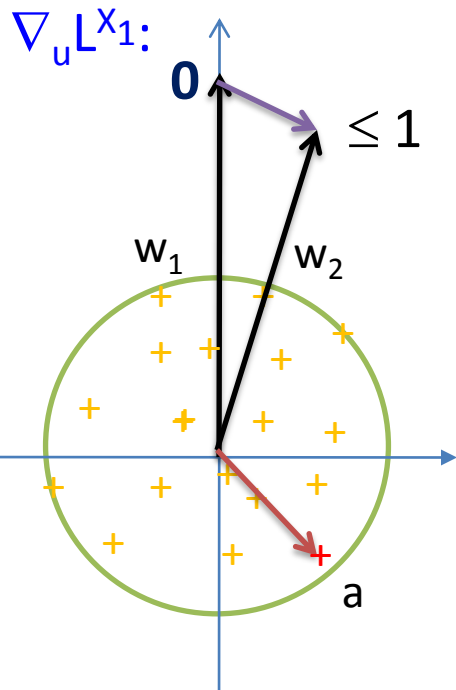
- Adding noise proportional to the global sensitivity.
  - Pick noise vector  $v$  with probability  $p(v) \propto e^{-\epsilon\lambda|v|}$
  - Output  $(w^* + v)$

On any line, the probability distribution of  $|v|$  is  $\text{Lap}(1/\epsilon\lambda)$



Claim:  $GS(LR) \leq 1/\lambda$

$$X_2 = X_1 + (a, 1)$$



$$L^{X_2}(w) = \lambda |w|^2 + \underbrace{\sum_i \log(1 + e^{-\langle x_i, w \rangle})}_{L^{X_1}(w)} + \underbrace{\log(1 + e^{-\langle a, w \rangle})}_{L^a(w)}$$

$$0 = \nabla_w L^{X_2}(w_2) = \nabla_w L^{X_1}(w_2) + \nabla_w L^a(w_2)$$

$$\frac{\langle a, u \rangle}{1 + e^{\langle w_2, a \rangle}} \leq 1$$

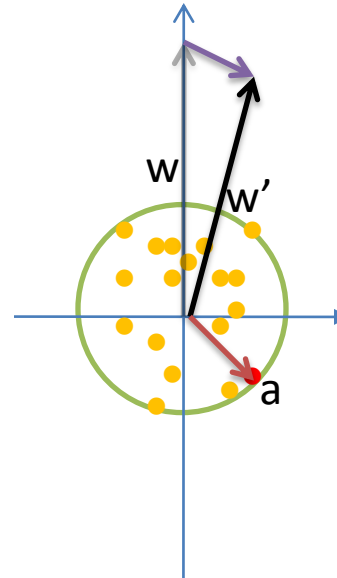
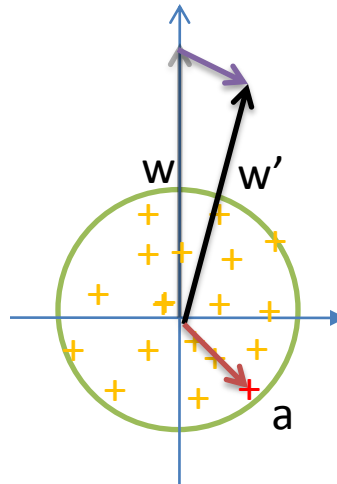
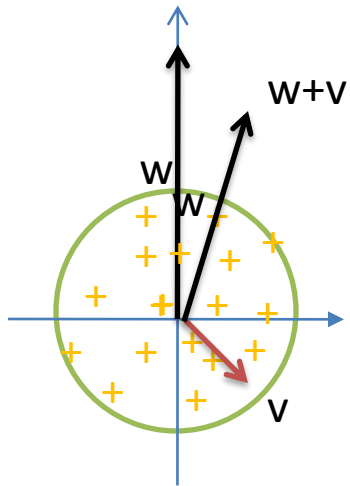
$$\nabla_u L^{X_1}(w_2) = -\nabla_u L^a(w_2) \leq 1$$

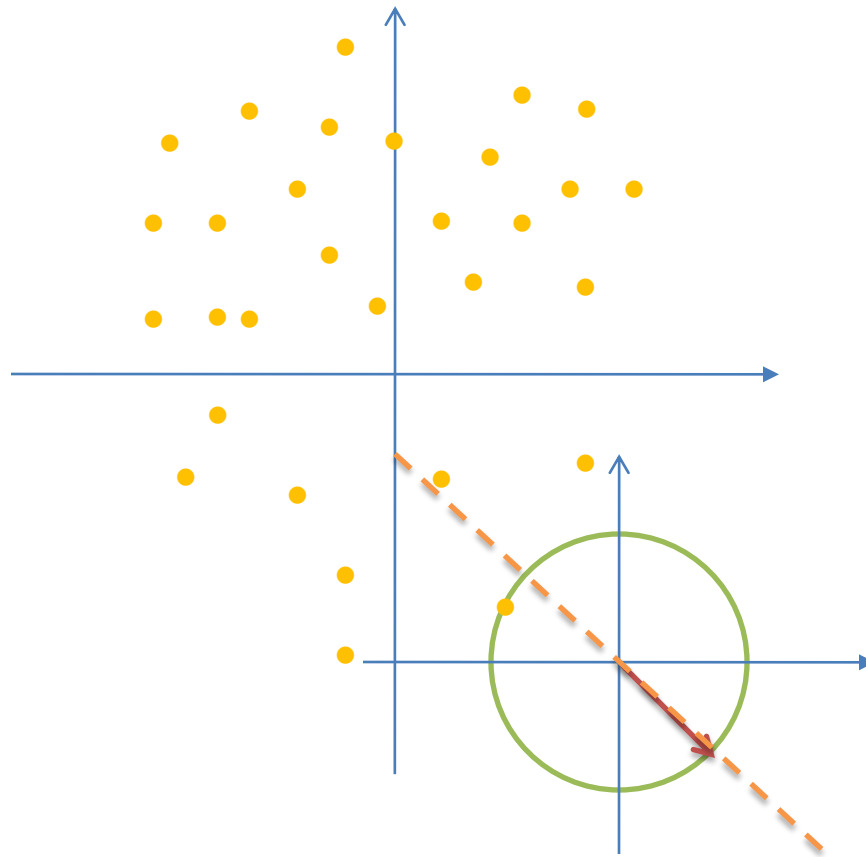
First derivative is the inner product along the line

$$\sum_i \frac{\langle x_i, u \rangle^2}{(1 + e^{-\langle w, x_i \rangle})(1 + e^{\langle w, x_i \rangle})} \geq 0$$

$$(\nabla_u)^2 L^{X_1}(w) = \lambda + T \geq \lambda$$

$$1 \geq \frac{\nabla_u L^{X_1}(w)}{\lambda} \geq \frac{1}{\lambda} \Rightarrow \lambda |w_1 + w_2|_2 \leq 1$$





Differentially Private

# Logistic Regression

Lots of previous works on differential privacy.

Add noise to achieve privacy

Tradeoff b/w privacy and utility

sensitivity of function

low sensitivity → less noise

# Roadmap

- Global sensitivity
  - [CM1]
- Local sensitivity
  - Our algorithm and [CM2]
- Directional local sensitivity
  - Add non-spherical noises
  - [CM2] and noisy gradient descent []