Transitive-Closure Spanners

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Based on joint work with

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and with

Graph Spanners [Awerbuch85,Peleg Schäffer89]

A subgraph H of G is a k-spanner if for all pairs of vertices u, v in G, $distance_H(u,v) \le k \ distance_G(u,v)$





dense graph G

sparse subgraph H

Goal: to find a sparsest *k*-spanner Applications:

- efficient routing
- protocols in unsynchronized networks
- parallel /distributed algorithms for approximate shortest paths

Transitive-Closure Spanners

G

Transitive closure TC(G) has an edge from u to v iff G has a path from u to v



k-**TC**-spanner *H* of *G* has $distance_H(u,v) \le k$ iff

G has a path from u to v



Alternatively: k-TC-spanner of G is a k-spanner of TC(G)

Example: Directed Line on *n* Vertices



• *k*-TC-spanner

 $O(n \log^* n)$ edges $O(n \lambda(k,n))$ edges

- Add a (k-2)-TC-spanner on hubs
- Connect each node to the hubs before and after
- Recurse on the fragments between hubs

Previous work

Structural results on TC-spanners (what is a sparsest k-TC-spanner for a given graph family?)

• Shortcut graphs (special case when $|E(H)| \le 2 |E(G)|$)

[Thorup 92, 95, Hesse 03]

- For directed line/trees [Thorup 97] *implicit in*
 - data structures [Yao 82, Alon Schieber 87, Chazelle 87, Bodlaender Tel Santoro 94]
 - property testing

[Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky 99]

- access control [Attalah Frikken Blanton 05]
- *New* For low-dimensional posets
 - access control [Attalah Blanton Fazio Frikken 09]

Computational results on directed spanners

(given a graph, compute a sparsest k-spanner)

- O(log n)-approximation algorithm for k=2 [Kortsarz Peleg 94]
- $O(n^{2/3} \operatorname{polylog} n)$ -approximation for k=3 [Elkin Peleg 99]

Our Contributions

- Common abstraction for several applications [BGJRW09]
 - property testing
 - testing monotonicity of functions
 - testing if a function $f:\{1,...,n\} \rightarrow \mathbb{R}$ is Lipschitz [Jha R]
 - access control
 - data structures
- Structural results on TC-spanners
 - path-separable graphs [BGJRW09]
 - directed hypercube/hypergrid [BGJRW]
 - low-dimensional posets [BGJRW]
- Computational results on directed spanners

k-TC-SPANNER: Given a graph, compute a sparsest k-TC-spanner

new algorithms, inapproximability results [BGJRW09]

Application 1: Testing if a List is Sorted

- Is a list of *n* numbers sorted?
 Requires reading entire list.
- Is a list of *n* numbers sorted or *ε*-far from sorted?
 (An *ε* fraction of list entries have to be changed to make it sorted.)
 [Ergün Kannan Kumar Rubinfeld Viswanathan 98]: O((log n)/ε) time
 [Fischer 01]: Ω(log n) queries

 Special case of testing monotonicity of functions defined in [Goldreich Goldwasser Lehman Ron 98]

Is a list sorted or ϵ -far from sorted?

[Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky 99]

Test can be viewed as: Pick a random edge from sparsest 2-TC-spanner for the line and compare its endpoints. Reject if they are out of order.



Claim 1. There are $\leq n \log n$ edges in the 2-TC-spanner.

Claim 2. Green numbers are sorted.

Proof: Any two green numbers are connected by a length-2 path of black edges Analysis of the test:

- All sorted lists are accepted.
- If a list is ϵ -far from sorted, it has $\geq \epsilon n$ red numbers, $\Rightarrow \geq \epsilon n/2$ red edges
 - If $\Theta((\log n)/\epsilon)$ edges are checked, a red edge will be discovered w.p. $\geq 2/3$

Is a list sorted or ϵ -far from sorted?

[Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky 99]

Test can be viewed as: Pick a random edge from sparsest 2-TC-spanner for the line and compare its endpoints. Reject if they are out of order.



Claim 1. There are $\leq n \log n$ edges in the 2-TC-spanner.

Claim 2. Green numbers are sorted.

Conclusion: It suffices to check $O((\log n)/\epsilon)$ random edges from 2-TC-spanner.

Observation:

The same test/analysis apply to any property of a list of numbers if

- it can be expressed in terms of pairs of numbers
- it is transitive: (x,y) and (y,z) are good \Rightarrow (x,z) is good

Generalization of Sortedness to Matrices

3 4 5 6 3 4 5 6 2 3 4 5 1 2 3 4

- Is a matrix sorted along all rows and columns or far from sorted (many numbers have to be changed to make it sorted)?
- [Goldreich Goldwasser Lehman Ron Samorodnitsky 00, Batu Rubinfeld White 99, Dodis Goldreich Lehman Raskhodnikova Ron Samorodnitsky 99, Halevy Kushilevitz 04] considered this problem for *d*-dimensional matrices.
- Is a function $f : \{1,...,m\}^d \to R$ monotone or ϵ -far from monotone? [DGLRRS99]: $O(d \cdot (\log m) \cdot (\log |R|) / \epsilon)$ time [Fischer Lehman Newman Raskhodnikova Rubinfeld Samorodnitsky 02]: for m = 2 and $R = \{0,1\}$, need $\Omega(\log \log d)$ queries

Monotonicity of Functions Over PO domains



Graph = partially ordered domain; node labels = values of the function

- A function is monotone if there are no violated edges (along which labels decrease):
 1
 0
- A function is ϵ -far from monotone if $\geq \epsilon$ fraction of labels need to be changed to make it monotone.
- Testing monotonicity is equivalent to several other testing problems.

Monotonicity Testers via Sparse 2-TC-spanners

Lemma. G has a 2-TC-spanner with s(n) edges $\downarrow \downarrow$

monotonicity of functions on G can be tested in time $O(s(n)/(\epsilon n))$

Implications of structural bounds on the size of 2-TC-spanners:

- Lower bounds for a hypercube and (hyper)grid [BGJRW]: TC-spanner method does not improve sortedness testers for matrices
- Upper bounds for other graph families [BGJRW09]:

better monotonicity testers for those graph families

e.g., for planar graphs run time improved from O($(n^{1/2} \log n)/\epsilon$) [FLNRRS02] to O($(\log^2 n)/\epsilon$)

Application 2: Access Control

Efficient key management in access hierarchies [Attalah Frikken Blanton 05, Attalah Blanton Frikken 06, Santis Ferrara Massuci 07, Attalah Blanton Fazio Frikken 09]

Used in content distribution, operating systems and project development



To speed up key derivation time, add shortcut edges consistent with permission edges

[Attalah Blanton Fazio Frikken 09]: access hierarchies are often low-dim posets (can be embedded into low-dim grids via order-preserving embeddings).

Steiner TC-spanners

In the access control application, one can add new nodes to the TC-spanner



- *H* is a Steiner *k*-TC-spanner of *G* if
- vertices(G) ⊆ vertices(H)
- $distance_{H}(u,v) \leq k$ if G has a path from u to v

 ∞ otherwise

Observation: Steiner vertices do not decrease the number of edges in sparsest TC-spanners of grids.

Application 3: Data Structures

Computing partial products in a semigroup [Yao 82, Alon Schieber 87, Chazelle 87, Bodlaender Tel Santoro 94, Thorup 97]



Goal: quickly answer queries $\max(a_i, ..., a_i)$ for all $i \leq j$.

- Question: How many values should we store if we want to compute max of at most k numbers per query?
- Answer: storage = size of sparsest *k*-TC-spanner for the directed line.

This example generalizes to other partial products and to directed trees.

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 - data structures
- Structural results on TC-spanners
 - path-separable graphs [BGJRW09]
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Structural Results on TC-spanners

Let $S_k(G)$ = size of sparsest k-TC-spanner of G

• Path-separable graphs [BGJRW09]

(e.g., H-minor-free graphs: planar, bounded genus, and bounded tree-width)

Path separators were defined in [Abraham Gavoille 06]

For O(1)-path-separable graphs G with n nodes, $S_k(G) = O(n \log n \cdot \lambda(k, n))$

- E.g., improves run time of monotonicity testers on planar graphs from O($(n^{1/2} \log n)/\epsilon$) [FLNRRS02] to O($(\log^2 n)/\epsilon$).
- Directed hypergrid [m]^d [BGJRW]
 - For small *m*:

 $\log_2(S_2([m]^d)) = c_m d$ where $c_2 \approx 1.16$, $c_3 \approx 2.03$, $c_4 \approx 2.82$

For reference: $[2]^d$ has $\Theta(2^d d)$ edges; TC($[2]^d$) has $3^d = 2^{cd}$ edges where $c \approx 1.59$

− For m≥3:

 $S_2([m]^d) \leq m^d \log^d m$, and this is tight up to $O(2d (\log \log m)^{d-1})$ factor.

 Monotonicity testers for hypercube/hypergrid cannot be improved using the TC-spanner method.

Structural Results on Steiner TC-spanners

Let $S_k(G)$ = size of sparsest Steiner *k*-TC-spanner of *G*

Low-dimensional posets

(posets embeddable into low-dim grids via order-preserving embeddings).

Previous work [Attalah Blanton Fazio Frikken 09, DeSantis Ferrara Masucci 07]

Setting of k	Bounds on $S_k(G)$	Authors
$k = 2d-2+i$ for $i \ge 2$	$O(n (\log^{d-1} n) \lambda(k,n))$	[ABFF]
$k = 2d + \log^* n$	$O(n \log^{d-1} n)$	[ABFF]
k = 3 for fixed d	$O(n \log^{d-1} n \log \log n)$	[DFM]

[BGJRW]

Setting of k	Our Bounds on S _k (G)		
<i>k</i> = 2	$O(n \log^d n)$ for all d	$\Omega(n (\log n / \log \log n)^d)$ for fixed d	
<i>k</i> ≥3		$n \log^{\Omega(d)} n$ for fixed d	

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2-TC-Spanner of an m×m Grid

Lemma. A sparsest 2-TC-spanner of an $m \times m$ grid has $\leq m^2 \log^2 m$ and $\Omega(m^2 \log^2 m / \log \log m)$ edges.

Proof:

Upper bound: graph product of two 2-TC-spanners of the line.

Lower bound: a tradeoff argument, balancing number of edges of different types.

Lower Bound for an m×m Grid: Starting Point

Lemma. A sparsest 2-TC-spanner of a line with m nodes has $\Omega(m \log m)$ edges.

Proof:



- Each pair of nodes connected by a green arc contributes an edge crossing the midline.
- \geq m/2 edges cross the midline.
- Continue recursively to obtain $\Omega(m \log m)$ bound.

Lower Bound for an m×m Grid: First Attempt

Approach: Recursively halve the grid in both dimensions hoping that each time $\Omega(m^2 \log m)$ edges are cut.



Problem: A 2-TC-spanner could contain the transitive closure for each quarter, and only $3m^2$ edges crossing the cut.

There is a tradeoff between the number of internal edges and the number of edges crossing the cut.

Two-Line Tradeoff Lemma

Lemma. Consider a 2-TC-spanner of an $m \times 2$ grid. Cut it horizontally. If it has $\leq m \log^2 m / 32$ internal edges, it has $\geq m \log^2 m / (16 \log \log m)$ crossing edges.



- log *m* / (2 log log *m*) stages, each contributing *m*/8 crossing edges.
- In the first stage, divide the graph into $\log^2 m$ blocks of the same length.
- Call an edge *long* if it starts and ends in different blocks (*short* otherwise).
- *L* = set of low left nodes, not incident to long crossing edges.

R = set of high right nodes, not incident to long crossing edges.

Two-Line Tradeoff Lemma: Stage 1 in the Proof

Lemma. Consider a 2-TC-spanner of an $m \times 2$ grid. Cut it horizontally. If it has $\leq m \log^2 m / 32$ internal edges, it has $\geq m \log m / (16 \log \log m)$ crossing edges.



- log *m* / (2 log log *m*) stages, each contributing *m*/8 crossing edges.
- In the first stage, divide the graph into $\log^2 m$ blocks of the same length.
- $u \in L$ can have a length-2 path to $v \in R$ only via a long internal edge.
- Each long low internal edge can be used by $\leq m/\log^2 m$ such pairs (*u*,*v*).
- If there are < m/8 long crossing edges, there are $> m^2/16$ pairs in $L \times R$.
- Then there are > $(m^2/16) / (m/\log^2 m) = m \log^2 m / 16$ (long) internal edges.
- Contradiction. That is, stage 1 indeed contributes *m*/8 long crossing edges.

Two-Line Tradeoff Lemma: Subsequent Stages

Lemma. Consider a 2-TC-spanner of an $m \times 2$ grid. Cut it horizontally. If it has $\leq m \log^2 m / 32$ internal edges, it has $\geq m \log^2 m / (16 \log \log m)$ crossing edges.



- $\log m / (2 \log \log m)$ stages, each contributing m/8 crossing edges.
- In each subsequent stage, call blocks from the previous stage *megablocks*.
- Divide each megablock into $\log^2 m$ blocks of the same length.
- Call an edge *long* if it starts and ends in different blocks, but stays within the same megablock.
- Show that there are m/8 long crossing edges (contribution of this stage).

2-TC-Spanner of the Grid:

Lemma. A sparsest 2-TC-spanner of an $m \times m$ grid has $\leq m^2 \log^2 m$ and $\Omega(m^2 \log^2 m / \log \log m)$ edges.

Lemma. A sparsest 2-TC-spanner of the directed grid $[m]^d$ has $\leq m^d \log^d m$ and $\Omega(m^d \log^d m / (2d (\log \log m)^{d-1}))$ edges.

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Computational Results on k-TC-SPANNER

S	Setting of k	Approxi- mability	Authors/ Technique	Notes
MN	<i>k</i> =2	O(log <i>n</i>)	[Kortsarz Peleg]	
ILL	<i>k</i> =3	$O(n^{2/3} \operatorname{polylog} n)$	[Elkin Peleg]	
Algo	<i>k</i> > 2	$O((n \log n)^{1-1/k})$	CP+sampling	Applies to directed spanners , Simplifies [EP] for <i>k</i> =3
	$k = \Omega(\log n)$	$O((n \log n)/k^2)$	path sampling	Better than directed spanners

Hardness	Setting of k	Inapproxi -mability	Assumption	Notes
	<i>k</i> = 2	$\Omega(\log n)$	$P \neq NP$	Matches upper bound
	constant <i>k</i> > 2	$\Omega(2^{\log^{1-\epsilon}n})$	NP \subseteq DTIME($n^{\text{polylog n}}$)	Improvement \Rightarrow breakthrough
	$k = n^{1-\gamma} \forall \gamma > 0$	$\Omega(1+\epsilon)$	$P \neq NP$	

Open Questions

- Can TC-spanner perspective be used to get new algorithms for problems related to monotonicity testing?
 - approximating distance to monotonicity or the length of LIS
 - online/distributed reconstruction of monotone functions
 - in streaming
- Other applications of TC-spanners and Steiner TC-spanners?